Autonics TCD220018AB

Independent Single Display PID Temperature Controllers



TR1D Series

PRODUCT MANUAL

For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

The specifications, dimensions, etc are subject to change without notice for product improvement Some models may be discontinued without notice.

Features

- · Compact, space-saving design with 22.5 mm width size
- 50 ms high-speed sampling and $\pm 0.3\%$ display accuracy
- Simultaneous heating/cooling function
- · Switch between current output and SSR drive output
- · Easy mount on DIN rails (patent)*1
- · RS485 communication output model available
- Protocol: Modbus RTU or ASCII
- Communication speed: up to 115,200 bps
- Parameter setting via PC (USB or RS485 communication)
- Comprehensive device management software (DAQMaster) provided
- · Heater disconnect alarm function (CT input)
- Current transformer (CT) sold separately: CSTC-E80LN, CSTC-E200LN, CSTS-E80PP Screen protection function
- *1 Korea Patent Registration 10-2019-0158569, Korea Design Registration 30-1065663, China Design Registration 202030164351.2

Safety Considerations

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- ▲ symbol indicates caution due to special circumstances in which hazards may occur.

⚠ Warning Failure to follow instructions may result in serious injury or death

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss.(e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.) ailure to follow this instruction may result in personal injury, economic loss or fire.
- 02. Do not use the unit in the place where flammable/explosive/corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.

Failure to follow this instruction may result in explosion or fire.

- **03. Install the unit on DIN rail to use.**Failure to follow this instruction may result in electric shock
- 04. Do not connect, repair, or inspect the unit while connected to a power

Failure to follow this instruction may result in fire or electric shock.

- 05. Check 'Connections' before wiring.
 - Failure to follow this instruction may result in fire.
- 06. Do not disassemble or modify the unit.

Failure to follow this instruction may result in fire or electric shock.

↑ Caution Failure to follow instructions may result in injury or product damage

01. When connecting the power input and relay output, use AWG 20 (0.50 mm²) cable or over, and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m.

When connecting the sensor input and communication cable without dedicated cable, use AWG 28 to 16 cable and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m.

Failure to follow this instruction may result in fire or malfunction due to contact

 ${\bf 02.}\ Use\ the\ unit\ within\ the\ rated\ specifications.$

Failure to follow this instruction may result in fire or product damage

- 03. Use a dry cloth to clean the unit, and do not use water or organic solvent. Failure to follow this instruction may result in fire or electric shock
- 04. Keep the product away from metal chip, dust, and wire residue which flow

Failure to follow this instruction may result in fire or product damage.

Cautions during Use

- Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents
- Check the polarity of the terminals before wiring the temperature sensor. For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length. For thermocouple (CT) temperature sensor, use the designated compensation wire for extending wire.
- Keep away from high voltage lines or power lines to prevent inductive noise In case of installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line.
- . Do not use near the equipment which generates strong magnetic force or high
- · Do not apply excessive power when connecting or disconnecting the connectors of the product.
- Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power.
- · Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature

- When changing the input sensor, turn off the power first before changing.

 After changing the input sensor, modify the value of the corresponding parameter.
- Do not overlapping communication line and power line. Use twisted pair wire for communication line and connect ferrite bead at each end of line to reduce the effect of
- Make a required space around the unit for radiation of heat. For accurate temperature
- measurement, warm up the unit over 20 min after turning on the power.

 Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.
- Do not wire to terminals which are not used.
- This unit may be used in the following environments.
- Indoors (in the environment condition rated in 'Specifications')
- Altitude Max. 2,000 m
- Pollution degree 2
- Installation category II

Ordering Information

Model	Control output1	Control output2	Option output	Additional function
TR1D-14RN	Relay	=	Alarm output 1	-
TR1D-14RR	Relay	Relay ↔ Alarm output 2	Alarm output 1	CT input
TR1D-R4RR	Relay	Relay ↔ Alarm output 2	Alarm output 1, Transmission output 1	CT input
TR1D-T4RR Relay		Relay ↔ Alarm output 2	Alarm output 1, RS485 communication	CT input
TR1D-14CN	Current/SSR	-	Alarm output 1	-
TR1D-14CC	Current/SSR	Current/SSR ↔ Transmission output 2	Alarm output 1	CT input
TR1D-R4CC Current/SSR		Current/SSR ↔ Transmission output 2	Alarm output 1, Transmission output 1	CT input
TR1D-T4CC Current/SSR		Current/SSR ↔ Transmission output 2	Alarm output 1, RS485 communication	CT input

Product Components

Product

· Instruction manual

Manual

For proper use of the product, refer to the manuals and be sure to follow the safety considerations in the manuals.

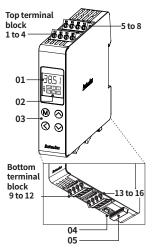
Download the manuals from the Autonics website.

Software

 $Download\ the\ installation\ file\ and\ the\ manuals\ from\ the\ Autonics\ website.$

DAQMaster is comprehensive device management program. It is available for parameter setting, monitoring.

Unit Descriptions



01. PV / SV display part (Red)

RUN mode: Displays PV (Present value) and SV (Setting value). Parameter: Displays name and setting value of parameters.

02. Indicator

 aicaco.					
Indicator	ON contition				
SV	SV display				
OUT	Control output□ ON				
AL1	AL1 alarm output ON				
•	The difference between PV and SV is less than 2°C				
▲/▼	The difference between PV and SV is greater than 2°C				
°C or °F	'2-2 Temperature unit' parameter setting				

03. Control key

[M]: MODE key [◀] / [▲] / [▼]: Setting value control key

04. PC loader port

Communication converter (SCM-USP, Sold separately) connection

05. Bracket handle

Use to mount and detach the DIN rail.

Specifications

Series		TR1D Series
Power su	ıpply	100 - 240 VAC ~ 50/60 Hz
Allowab	le voltage range	90 to 110% of rated voltage
Power co	onsumption	≤8 VA
Samplin	g period	50, 100, 250 ms
Input sp	ecification	Refer to 'Input Type and Using Range'.
Option input	CT input	•0.0-50.0 A (primary current measurement range) •CT ratio: 1/1,000, •Measurement accuracy: ±5% F.S. ±1digit
	Relay	250 VAC~ 3 A 1a
Control output	SSR	$12 \text{ VDC} = \pm 3 \text{ V}, \le 20 \text{ mA}$
output	Current	DC 4-20 mA or DC 0-20 mA (parameter), Load: \leq 500 Ω
	Alarm	AL1, AL2: 250 VAC∼ 3 A 1a
Option output	Transmission	DC4-20 mA (Load resistance: \leq 500 Ω , Output accuracy: \pm 0.3% F.S.)
	RS485 comm.	Modbus RTU / ASCII
Dicplaytype		7 cogmont (rod) 4 digit

Display typ	e	7 segment (red), 4-digit				
Control typ	oe .	ON/OFF, P, PI, PD, PID Control				
Hysteresis		Control output: 1 to 100 °C/°F (0.1 to 100.0 °C/°F) Alarm output: 1 to 100 °C/°F (0.1 to 50.0 °C/°F)				
Proportion	al band (P)	0.1 to 999.9 °C				
Integral tir	ne (I)	0 to 9,999 sec				
Derivative	time (D)	0 to 9,999 sec				
Control cy	cle (T)	Relay output: 0.5 to 120.0 sec, SSR drive output: 0.5 to 120.0 sec				
Manual res	et	0.0 to 100.0%				
Dielectric s	trength	Between the charging part and the case : 3,000 VAC ~ 50/60 Hz for 1 min				
Vibration		0.75 mm amplitude at frequency of 5 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours				
Relay life	Mechanical	OUT1/2, AL1/2: ≥ 5,000,000 operations				
cycle	Electrical	OUT1/2, AL1/2: \geq 100,000 operations (resistance load: 250 VAC \sim 5 A)				
Insulation	resistance	≥ 100 MΩ (500 VDC megger)				
Insulation	type	Double insulation or reinforced insulation (dielectric strength between the charging part and the case: 3 kV)				
Noise imm	unity	Square shaped noise (pulse width: 1 μ s) by noise simulator ± 2 kV R-phase, S-phase				
Memory re	tention	≈ 10 years (non-volatile semiconductor memory type)				
Ambient to	mperature	-10 to 50 °C, storage: -20 to 60 °C (no freezing or condensation)				
Ambient h	umidity	35 to 85%RH, storage: 35 to 85%RH (no freezing or condensation)				
Approval		C € EHL				
Unit weigh	t (packaged)	≈ 123.5 g (≈ 194.5 g)				

Communication Interface

■ RS485

Communication protocol	Modbus RTU / ASCII				
Application standard	EIA RS485 compliance with				
Maximum connection	31 units (address: 01 to 127)				
Synchronous method	Asynchronous				
Communication method	Two-wire half duplex				
Communication effective range	≤ 800 m				
Communication speed	4,800 - 9,600 (default) - 19,200 - 38,400 - 57,600 - 115,200 bps (parameter)				
Response time	5 to 99 ms (default: 20 ms)				
Start bit	1 bit (fixed)				
Data bit	8 bit (fixed)				
Parity bit	None (default), Odd, Even				
Stop bit	1 bit, 2 bit (default)				
EEPROM life cycle	≈ 1,000,000 operations (Erase / Write)				
It is an an an an and ad to the Atlanti					

It is recommended to use Autonics communication converter. Please use twisted pair wire, which is suitable for RS485 communication.

Input Type and Using Range

• The setting range of some parameters is limited when using the decimal point display.

Input typ	oe .	Decimal point	Display Method	Using range(°C)	Using range(°F)	
	K (CA)	1	F E WH	-50 to 1,200	-58 to 2,192	
	K (CA)	0.1	E C A.L	-50.0 to 999.9	-58.0 to 999.9	
	J (IC)	1	JI C.H	-30 to 800	-22 to 1,472	
	J (IC)	0.1	JI E.L	-30.0 to 800.0	-22.0 to 999.9	
Thermo	L (IC)	1	LIE.H	-40 to 800	-40 to 1,472	
-couple	L (IC)	0.1	LIE.L	-40.0 to 800.0	-40.0 to 999.9	
	T (CC)	1	£ € €.H	-50 to 400	-58 to 752	
		0.1	E C C.L	-50.0 to 400.0	-58.0 to 752.0	
	R (PR)	1	rPr	0 to 1,700	32 to 3,092	
	S (PR)	1	SPr	0 to 1,700	32 to 3,092	
	DPt100 Ω	1	dPt.H	-100 to 400	-148 to 752	
	DP(10012	0.1	dPt.L	-100.0 to 400.0	-148.0 to 752.0	
RTD	CU50 Ω	1	C U 5.H	-50 to 200	-58 to 392	
	CU3012	0.1	C U 5.L	-50.0 to 200.0	-58.0 to 392.0	
	Nickel120 Ω	1	ul 15	-80 to 260	-112 to 500	

■ Display accuracy

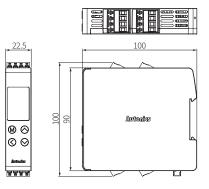
• The setting range of some parameters is limited when using the decimal point display.

Input type	Using temperature	Measurement accuracy
Thermocouple RTD	At room temperature (23°C±5°C)	$\label{eq:continuous} \begin{split} &(\text{PV}\pm0.3\% \text{ or }\pm1^\circ\text{C higher one})\pm1\text{-digit} \\ &\cdot\text{Thermocouple R (PR), S (PR) below 200^\circ\text{C}:} \\ &(\text{PV}\pm0.5\% \text{ or }\pm3^\circ\text{C higher one})\pm1\text{-digit,} \\ &\text{Over 200}^\circ\text{C}: \\ &(\text{PV}\pm0.5\% \text{ or }\pm2^\circ\text{C higher one})\pm1\text{-digit,} \\ &\cdot\text{Thermocouple L (IC), RTD Cu50}\Omega: \\ &(\text{PV}\pm0.5\% \text{ or }\pm2^\circ\text{C higher one})\pm1\text{-digit} \end{split}$
	Out of room temperature range	$ \begin{array}{l} (\text{PV}\pm0.5\% \text{ or } \pm2^{\circ}\text{C higher one}) \pm 1\text{-digit} \\ \bullet \text{Thermocouple R (PR), S (PR):} \\ (\pm1.0\% \text{ or } \pm5^{\circ}\text{C higher one}) \pm 1\text{-digit} \\ \bullet \text{Thermocouple L (IC), RTD Cu50 } \Omega: \\ (\text{PV}\pm0.5\% \text{ or } \pm3^{\circ}\text{C higher one}) \pm 1\text{-digit} \end{array} $

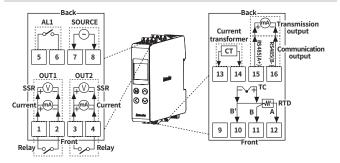
⁺ When multiple products (or more) are mounted without separation, $\pm 1^{\circ}\text{C}$ is added to all accuracy.

Dimensions

• Unit: mm, For the detailed drawings, follow the Autonics website.



Connections



■ Terminal support by model

Terminal No.	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16		
Function Model	Con	trol put 1	Control output 2		Alarm output Power		-	Temperature sensor input			CT input		Option output					
TR1D-14RN	Rela	ıy	-		Rel	ay	0		-	TC RTD)	-	-	-	-	-		
TR1D-14RR	Rela	ıy	Rela	Relay		ay	0		-	TC RTD)	-	0		-	-		
TR1D-R4RR	Rela	ıy	Relay		Rel	Relay 🔾		-	TC - RTD		-	0		Trans -mission				
TR1D-T4RR	Rela	ıy	Rela	у	Rel	ay	0		-	TC - RTD		-	0		Communi -cation			
TR1D-14CN	Curr		-		Relay		Relay		0		-	TC RTD)	-	-	-	-	-
TR1D-14CC	Curr		Curr	ent	Rel	ay	0		-	TC RTD)	-	0		-	-		
TR1D-R4CC	Curr		Curr	ent	Rel	ay	0		-	TC RTD)	-	0		Tran			
TR1D-T4CC	Curr		Curr	ent	Rel	ay	0		-	TC RTD)	-	0		Com-cati	muni on		

Initial Display When Power is ON

When power is supplied, after all display will flash for a while, series and model name are displayed sequentially. After input sensor type will flash twice, enter into RUN mode.

All display	Series	Model	Input specification	Run mode	
8888. ♣ SV°F°C ♥ 001007AL1	Er Id	<u></u>	PEAH ©C	25.5 cc	

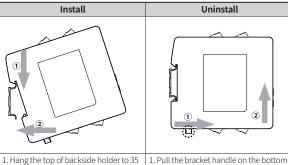
Errors

Display	Description	Troubleshooting	
oPEn	Flashes if input sensor is disconnected or sensor is not connected.	Check input sensor status.	
нннн	Flashes when PV is higher than input range.	When input is within the rated	
LLLL	Flashes when PV is lower than input range.	temperature range, this display disappears.	

Installation Method

■ Mounting on DIN rail

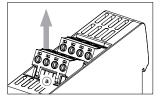
• Mount the metal part with a spanner so that a large force is not applied to the body.

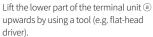


- mm width DIN rail.
- 2. Press the unit in the direction of the arrow until there is clicking sound.
- 1. Pull the bracket handle on the bottom of the unit in the direction of the arrow. 2. Lift the unit up while pulling the handle
- bracket to remove.

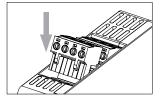
Attaching and Dettaching a Terminal Unit

Detaching





Attaching



Press the terminal unit downwards to insert.

• When disconnecting terminal unit and wiring, refer to 'Connections' to attach to right position. Failure to follow this instruction may result in fire product damage or malfunction.

Mode Setting Display part [▲] key over 2 sec switching No key input over Screen [MODE], $[\blacktriangleleft]$, $[\blacktriangle]$, $[\blacktriangledown]$ key \rightarrow screen protection protection + [▲] key over 3 Digital input key RUN Auto RUN [MODE] key or no key input over 3 sec [MODE], [**◀**], [**▲**] or SV setting [▼] key **Parameter** [MODE] key over 2 [MODE] key over 2 sec group [**4**] + [**4**] + [**7**] kev Parameter reset Auto

Parameter Setting

- Some parameters are activated/deactivated depending on the model or setting of other parameters. Refer to the descriptions of each item.
- Select group by $[\blacktriangle], [\blacktriangledown]$ key and press [MODE] key to parameter setting mode in parameter group setting mode.
- [MODE] key: Move to next item after saving / Return to upper level with save (\geq 2 sec) [\blacktriangleleft] key: Move digits / Return to the upper level without saving (\ge 2 sec) / Return to RUN mode without saving (≥ 3 sec)
- [lack lack la
- Return to the upper level without saving when there is no key input for more than 30 seconds.
- \bullet The range in parentheses '()' is the setting range when the set value of the 'input specification' parameter is used with one decimal point.
- Recommended parameter setting sequence: Parameter 2 group \rightarrow Parameter 1 group → SV setting mode

■ Parameter 1 group

■ Parameter 1 group										
ameter	Display	Default	Setting range	Condition						
Lock	rocr	oFF	OFF LOC1: Lock parameter 2 group LOC2: Lock parameter 1, 2 group LOC3: Lock parameter 1, 2 group + SV setting lock + it is possible to check the value only in lock mode.	-						
Heater current monitoring	C E - A	-	[CT input model] 0.0 to 50.0 A	2-10/11 Control output 1/2: SSR						
Auto tuning	ЯĿ	oFF	OFF, ON: Execution	2-9 Control type: PID						
AL1 alarm temperature	ALI	1250	Deviation alarm: -F.S. to F.S. °C/°F Absolute value alarm: Within input specification • Changing the '2-16/19 AL1/2 alarm	2-16/19 AL1/2 alarm						
AL2 alarm temperature	AL 2	1250	operation' and '2-17/20 AL1/2 alarm option' will automatically reset the value to the maximum or minimum that will not be output.	operation: AM1 to AM6, HBA						
Heating proportional band	н-Р	10	0.1 to 999.9 °C/°F	-						
Heating integral time	H - I	240	0 (OFF) to 9999 sec	-						
Heating derivative time	Н- d	49	0 (OFF) to 9999 sec	-						
Cooling proportional band	[- P	10	0.1 to 9999 °C/°F	-						
Cooling integral time	E - I	240	0 (OFF) to 9999 sec	-						
Cooling derivative time	[- d	49	0 (OFF) to 9999 sec	-						
Dead band 01)	dЬ	0	-Proportional band to +Proportional band °C/°F	2-9 Control type: P.P, P.ON, ON.P						
			-999 to 999 (-199.9 to 999.9) °C/°F	2-9 Control type: ON.ON						
Manual reset	r E S E	50	0.0 to 100.0%	1-7/10 Heating/ Cooling integral time: 0						
Heating hysteresis	н.н ч 5	5	1 to 100 (0.1 to 100.0) °C/°F	2-9 Control						
Heating OFF offset	H.o 5 Ł	0	0 to 100 (0.0 to 100.0) °C/°F	type: ONOF &						
Cooling hysteresis	C.H Y S	5	1 to 100 (0.1 to 100.0) °C/°F	2-8 Control output mode						
Cooling OFF offset	C.o 5 Ł	٥	0 to 100 (0.0 to 100.0) °C/°F							
	Lock Heater current monitoring Auto tuning AL1 alarm temperature AL2 alarm temperature Heating proportional band Heating integral time Heating derivative time Cooling integral time Cooling integral time Locoling integral time Cooling integral time Locoling integral time Cooling of cooling integral time Cooling integral time Cooling of cooling integral time Cooling integral time Cooling of coo	Heater current monitoring Auto tuning AL1 alarm temperature Heating proportional band Heating integral time Cooling proportional band Cooling integral time Cooling integral time Cooling integral time Cooling band Cooling integral time Cooling time Cooling integral time Cooling integra	Heating proportional band Heating derivative time Cooling Integral time Cooling derivative time Dead band	Lock Lock						

⁰¹⁾ When set to the + value, the dead band is formed based on SV and does not control any control.

When set to the - value, the overlap band is formed based on SV, perform the heating and cooling control at the same time.

⁰²⁾ Parameter display following to the setting value of '2-8 Control output mode' HEAT: '1-14 & 15 Heating hysteresis & OFF offset' COOL: '1-16 & 17 Cooling hysteresis & OFF offset' H-C: '1-14 & 15 Heating hysteresis & OFF offset', '1-16 & 17 Cooling hysteresis & OFF offset'

	Parameter 2	group)		
_	meter	Display		Setting range	Condition
2-1	Input specification	In-E		Refer to 'Input Type and Using Range'	-
2-2	Temperature unit	Unit		°C, °F	-
2-3	Sampling period	5PL.E		50, 100, 250 ms	-
2-4	Input correction	1 n - b		-999 to 999 (-199.9 to 999.9) °C/°F	-
2-5	Input digital filter SV low limit value	ñ A u.F L − 5 u		0.1 to 120.0 sec Within 2-1 Input specification	-
				1_SV < H_SV _ 1_digit °C /°E	
2-7	SV high limit value	H-5u	1500	H-SV ≥ L-SV + 1-digit °C/°F	-
2-8	Control output	o-Ft	н- [HEAT: Heating ⁰¹⁾ , COOL: Cooling ⁰¹⁾ ,	_
	mode			H-C: Heating&Cooling®	* 2 0 C+I
2-9	Control type	[-ñd	PP	PID, ONOF: ON/OFF, P.P: PID-PID*, ON.ON: ON/OFF-ON/OFF*, P.ON: PID-ON/OFF*,	* 2-8 Control output mode:
2 3	control type		· · ·	ON.P: ON/OFF-PID*	H-C
2-10	Control output 1	oUt I	Curr	[Current/SSR output model]	
2-11	Control output 2	oUF5	20	SSR, CURR: Current	
2-12	Control output 1 range	o lāA			2-10/11 Control
	Control output 2		4-20	4-20, 0-20 mA	output 1/2:
2-13	range	0 Z.ñ A			CURR
			20.0	[Relay output model]	
2-14	Heating control	H-E	2 0.0	0.5 to 120.0 sec	
	cycle	" -	2.0	[Current/SSR output model]	2-10/11 Control
				[Relay output model]	output 1/2: SSR
0.45	Cooling control		2 0.0	0.5 to 120.0 sec	-
2-15	cycle	[-E	2.0	[Current/SSR output model]	2-10/11 Control
				0.5 to 120.0 sec	output 1/2: SSR
				AMO: OFF	
				AM0: OFF AM1: Deviation high limit alarm	
				AM2: Deviation low limit alarm	
				AM3: Deviation high, low limit alarm	
2-16	AL1 alarm			AM4: Deviation high, low limit reserve	_
2 10	operation			alarm	
				AM5: Absolute value high limit alarm AM6: Absolute value low limit alarm	
		81 - 1	RA LR	SBA: Sensor break alarm	
				LBA: Loop break alarm	
				HBA: Heater break alarm	
				A. Ctandard alarma D. Alarma Intala Co	
				A: Standard alarm, B: Alarm latch, C: Standby sequence 1, D: Alarm latch and	
2-17	AL1 alarm option			sequence 1, E: Standby sequence 2, F:	-
				Alarm latch and sequence 2	
				Enter to option setting: Press [◀] key in	
				2-16 AL-1 alarm operation.	2-16/17
2.10	A1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		١.	11, 100 (0.1), 50 0) 95 (95	AL1/2 Alarm
2-18	AL1 Hysteresis	A IHA	1	1 to 100 (0.1 to 50.0) °C/°F	operation: AM1
					to AM6 or HBA
2-19	AL2 alarm operation		0-10	[Alarm output 2 model]	2-8 Control
2-20	AL2 alarm option	AL-2	HO !.H	Same as '2-16/17 AL1 alarm operation/ option'	output mode: HEAT or COOL
				option .	2-16/17
2-21	AL2 hysteresis	R 2.H 9	1	[Alarm output 2 model]	AL1/2 Alarm
2-21	ALZ Hysteresis	116.113	· '	1 to 100 (0.1 to 50.0) °C/°F	operation: AM1
2 22	LBA time (33)	L b R.E		0 to 9999 sec or auto setting (4)	to AM6 or HBA 2-16/17
				0 to 000 (0 0 to 000 0) °C (°F or Auto sotting	
2-23	LBA band	L b R.b	2	05)	operation: LBA
	Transmission			[Transmission output model]	i i
2-24	output1 mode	8 o. ñ 1	Pu	PV, SV, H-MV: Heating MV, C-MV: Cooling	
				MV	
2-25	Transmission output1 low limit	F5 I.L	-50	[Transmission output model]	[
	Transmission		,	I ransmission output model Refer to 'Input Type and Using Range'	
2-26	output1 high limit	F5 LH	1500		
2-27	Transmission	Ro.ñ2	ρυ	[Transmission output 2 model]	
	output2 mode		, ,	PV, SV, H-MV: Heating MV, C-MV: Cooling MV	2-8 Control
2-28	Transmission output2 low limit	F5 I.L	-50	[Transmission output 2 model]	output mode:
	Transmission			[Transmission output 2 model] Refer to 'Input Type and Using Range'	HEAT or COOL
2-29	output2 high limit	F5 LH	1500		
2-30	Digital input key	d1 - E	StoP	STOP: Stop control output, ALRE: Alarm	_
		" "	5.07	reset, AT: Auto tuning execution, OFF	200 : :
				0.0 (OEE) to 100.0 (ON)	2-8 Control
				0.0 (OFF) to 100.0 (ON)	output mode: HEAT or COOL
2-31	Sensor error, MV	Er.ñu	0		2-8 Control
				-100 (Cooling ON) to 0.0 (OFF) to 100	output mode:
				(Heating ON)	H-C
2-32	Screen protection	d5P		OFF, 1, 30, 60 min	-
	Comm. protocol	PrEL		RTU: Modbus RTU, ASCI: Modbus ASCII	-
	Comm. address	Adr5		1 to 99	-
	Comm. speed Comm. parity bit	bP5 Prty		48, 96, 192, 384, 576, 1152 (×100) bps None, Even, Odd	<u> </u>
	Comm. parity bit	SEP		1, 2 bit	-
	Response time	-54.E		5 to 99 ms	-
2-39		Cony		EN.A: Enable, DIS.A: Disable	
2-40		Init		YES, NO	-

01) [Alarm output2 model] 'Control output 2 terminal' operates as 'alarm output 2'. [Transmission output2 model] 'Control output 2 terminal' operates as 'transmission output 2'.

02) [Control output 2 terminal not support model] 'Alarm output 1 terminal' operates as 'control output 2'.

(02) (Control output 2 terminal not support model) Alarm output 1 terminal operates as control output 2.

(3) - Initialization condition of LBA time (alarm output status)
Alarm reset, change '2-8 Control output mode' (standard alarm: OFF, alarm latch: OFF),
Change '2-4 Input correction' or SV (Standard alarm: latch, alarm latch: latch),
Error status: OPEN, HHHH, LLLL (standard alarm: Immediately ON, alarm latch: latch)
- Stop condition of LBA operation (Alarm output status)
Set '2-22/23 LBA time/band: 0' (standard alarm: OFF, alarm latch: latch)
Stop control output, execute auto tuning (standard alarm: OFF, alarm latch: latch),
If '2-1 Input specification' is changed, the settings are initialized.

O4) After auto tuning, the range is set as twice of the integral time automatically. If the previous setting value is outside of the range automatically set, it is set to the nearest Max. or Min. value of the range.

O5) After auto tuning, the range is set as 10% of the proportion band automatically. If the previous setting value is outside of the range automatically set, it is set to the nearest Max. or Min. value of the range.

Function: Alarm

888.8 Alarm Alarm operation option Set both alarm operation and alarm option by combining. Each alarm operates individually in two alarm output models. When the current temperature is out of alarm range, alarm clears automatically.

Operation

• **H**: Alarm output hysteresis

Name	Alarm operation	Description				
-	-		No alarm output			
Deviation high limit	OFF H ON SV PV 100°C 110°C High deviation: Set as 10°C	OFF H ON PV SV 90°C 100°C High deviation: Set as -10°C	If deviation between PV and SV as high-limit is higher than set value of deviation temperature, the alarm output will be ON.			
Deviation low limit	ON H OFF A SV 90°C 100°C Low deviation: Set as 10°C	ON TH OFF SV PV 100°C 110°C Low deviation: Set as -10°C	If deviation between PV and SV as low limit is higher than set value of deviation temperature, the alarm output will be ON.			
Deviation high, low limit	ON H ON PV SV 90°C 1000	If deviation between PV and SV as high/low-limit is higher than set value of deviation temperature, the alarm output will be ON.				
Deviation high, low limit reverse	OFF H O PV 90°C 100 High, Low devia	If deviation between PV and SV as high/low-limit is lower than set value of deviation temperature, the alarm output will be OFF.				
Absolute value high limit	OFF H ON PV SV 90°C 100°C Absolute value: Set as 90°C	OFF H ON SV PV 100°C 110°C Absolute value: Set as 110°C	If PV is higher than the absolute value, the output will be ON.			
Absolute value low limit	ON TH OFF A PV SV 90°C 100°C Absolute value: Set as 90°C	ON TH OFF SV PV 100°C 110°C Absolute value: Set as 110°C	If PV is lower than the absolute value, the output will be ON.			
Sensor break	-		It will be ON when it detects sensor disconnection.			
Heater break	-		It will be ON when it detects heater disconnection.			
Loop break	-		It will be ON when it detects loop disconnection.			

Option

Name	Description	Condition of re-apply	
Standard alarm	If it is an alarm condition, alarm output is ON. If it is a clear alarm condition, alarm output is OFF.	-	
Alarm latch	If it is an alarm condition, alarm output is \ensuremath{ON} and maintains \ensuremath{ON} status.	=	
Standby sequence 1	First alarm condition is ignored and from second alarm condition, standard alarm operates. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second alarm condition, standard alarm operates.	Power ON	
Alarm latch and standby sequence 1	If it is an alarm condition, it operates both alarm latch and standby sequence. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second Jalarm condition, alarm latch operates.		
Standby sequence 2			
Alarm latch and standby sequence 2	Basic operation is same as alarm latch and standby sequence1. It operates not only by power ON/OFF, but also alarm set value, or alarm option changing. When re-applied standby sequence and if it is alarm condition, alarm output does not turn ON. After clearing alarm condition, alarm latch operates.	temperature / operation or change STOP to RUN mode	

Segment Table

7 Segment			11 Segment			12 Segment			16 Segment						
0	0	1	П	0	0	1	1	0	0	1	1	0	0	Ι	П
-1	1	J	J	-1	1	J	J	-1	1	J	J	-1	1	ŭ	J
2	2	F	К	2	2	К	К	2	2	К	К	2	2	K	К
3	3	L	L	3	3	L	L	3	3	L	L	3	3	L	L
4	4	ñ	М	Ч	4	М	М	Ч	4	М	М	Ч	4	М	М
5	5	n	N	5	5	N	N	5	5	N	N	5	5	И	N
5	6	0	0	Б	6	0	0	Б	6	٥	0	Б	6	0	0
7	7	Ρ	Р	7	7	Р	Р	7	7	ρ	Р	7	7	Р	Р
8	8	9	Q	8	8	Q	Q	8	8	O	Q	8	8	Q	Q
9	9	۲	R	9	9	R	R	9	9	R	R	9	9	ĸ	R
Я	Α	5	S	Я	Α	5	S	Я	Α	5	S	Я	Α	5	S
ь	В	Ł	Т	Ь	В	Ł	Т	Ь	В	Ł	Т	3	В	T	Т
Ε	С	П	U	Ε	С	П	U	Ε	С	Ш	U	Е	С	U	U
Ь	D	u	V	Ь	D	ľ	V	Ь	D	V	V	D	D	V	٧
Ε	Е	ū	W	Ε	Е	И	W	Ε	Е	И	W	Ε	Е	И	W
F	F	4	Х	F	F	×	Х	F	F	×	Х	F	F	×	Х
G	G	У	Υ	G	G	У	Υ	5	G	У	Υ	5	G	Y	Υ
Н	Н	Ξ	Z	Н	Н	7	Z	Н	Н	7	Z	Н	Н	2	Z