Autonics

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- $\underline{\Lambda}$ symbol indicates caution due to special circumstances in which hazards may occur.
- Marning Failure to follow instructions may result in serious injury or death
- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.) Failure to follow this instruction may result in personal injury, economic loss or fire.
- Do not use the unit in the place where flammable/explosive/corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.
- Failure to follow this instruction may result in explosion or fire. 03. Install on a device panel to use.
- Failure to follow this instruction may result in fire.
- 04. Do not connect, repair, or inspect the unit while connected to a power source.
- Failure to follow this instruction may result in fire. **05. Check 'Connections' before wiring.**

Safety Considerations

Failure to follow this instruction may result in fire. **06. Do not disassemble or modify the unit.** Failure to follow this instruction may result in fire.

Caution Failure to follow instructions may result in injury or product damage

- 01. When connecting the power input and relay output, use AWG 26 to 12 cable and connecting the sensor input and communication cable without dedicated cable, use AWG 28 to 14 cable. Failure to follow this instruction may result in fire or malfunction due to contact failure.
- 02. Use the unit within the rated specifications.
- Failure to follow this instruction may result in fire or product damage 03. Use a dry cloth to clean the unit, and do not use water or organic solvent. Failure to follow this instruction may result in fire or electric shock.
- 04. Keep the product away from metal chip, dust, and wire residue which flow into the unit.

Failure to follow this instruction may result in fire or product damage.

Cautions during Use

- Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
- Check the polarity of the terminals before wiring the temperature sensor. For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length.

For thermocouple (CT) temperature sensor, use the designated compensation wire for extending wire.

- Keep away from high voltage lines or power lines to prevent inductive noise.
 In case of installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line.
 Do not use near the equipment which generates strong magnetic force or high
- frequency noise.Do not apply excessive power when connecting or disconnecting the connectors of the product.
- Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power.
- Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature controller.
- When changing the input sensor, turn off the power first before changing. After changing the input sensor, modify the value of the corresponding parameter.

Modular 2/4-Channel PID Temperature Controllers with Screwless Connector



TM Series PRODUCT MANUAL

For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

The specifications, dimensions, etc are subject to change without notice for product improvement Some models may be discontinued without notice.

Features

- Multi-channel (4-channel : TM4/2-channel : TM2) input and output control
- High-speed sampling cycle (4-channel : 100ms/2-channel : 50ms)
- Module connection and expansion with expansion connectors
- Communication between modules
- No additional power supply wiring
- Expandable up to 31 units (124-channels/62-channels)
- Simultaneous heating and cooling control function
- Isolated input channels (dielectric strength : 1000VAC)
- Switch between current output and SSR drive output (TM2- 2C)
- Parameter configuration via PC (USB and RS485 communication)
- DAQMaster software included (comprehensive device management software)
 Communication converter sold separately : SCM-US (USB to serial converter), SCM-381 (RS-232C to RS485 converter), SCM-US481 (USB to RS485 converter)
- Easy wiring and maintenance with various connectors : sensor input connector, control output connector, power/communication connector
- Heater disconnect alarm function (CT input)
- Current transformer (CT) sold separately : CSTC-E80LN, CSTC-E200LN
- Various input types and temperature ranges



- 24 VDC== model power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
- Do not overlapping communication line and power line.
 Use twisted pair wire for communication line and connect ferrite bead at each end of line to reduce the effect of external noise.
- Make a required space around the unit for radiation of heat.
- For accurate temperature measurement, warm up the unit over 20 min after turning on the power.
- Mounting multiple devices in any way other than the specified mounting method may cause heat to build up inside, which will shorten their service life. If there is a possibility of the ambient temperature rising to a temperature above the specified temperature range, take steps, such as installing fans, to cool the device. Be sure that the cooling method in not cooling just the terminal block. If only the terminal block is cooled, measurement errors may occur.
- Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.
- Do not wire to terminals which are not used.
- Install DIN rail vertically from the ground.
 This upit may be used in the following emvire
- This unit may be used in the following environments.
 Indoors (in the environment condition rated in 'Specifications')
- Altitude Max. 2,000 m
- Pollution degree 2
- Installation category II

Ordering Information

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website .

т	М	0	-	2	2	3	4	
0 chan			-	Contro	output	:		
2: 2 char	nnels		R:	Relay				
4: 4 char	nnels		S:	SSR driv	e			
Alarn	n output		C:	Selectab	le curre	nt or SSR	drive output	
	output 1 nnels)	/2	-	Structu Basic mo				
4: Alarm	output 1	/2/3/4	E:	Expansio	on modu	ıle		
· · ·	nnels) (4 chann	olc)	 Since the expansion module is not supplied with power/ comm. terminal. Use it with the basic module. 					

Instruction manual

Product Components

- Product
- Side connector: 1
- Power/Comm. connector: 1 (only for basic module)

Sold Separately

Communication converter: SCM-Series
 Current transformer (CT)

Manual

For proper use of the product, refer to the manuals and be sure to follow the safety considerations in the manuals.

Download the manuals from the Autonics website.

Software

Download the installation file and the manuals from the Autonics website.

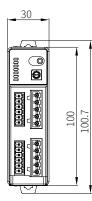
DAQMaster

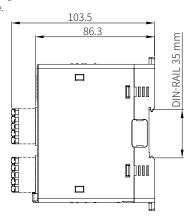
DAQMaster is comprehensive device management program. It is available for parameter setting, monitoring.

Dimensions

• Unit: mm, For the detailed drawings, follow the Autonics website.

Below is based on basic module.





Spec	ification	S							
Series		TM2	TM4						
No. of ch	annels	2 channels 4 channels							
Power su	vlaa	24 VDC== ±10%							
Allowabl									
range	-	90 to 110% of rated voltage							
Power co	nsumption	≤ 5 W (for Max. load)							
Sampling	gperiod	50 ms (2 channels synchronous sampling)	100 ms (4 channels synchronous sampling)						
Input spe	cification	Refer to 'Input Type and Using Range'.							
	CT input	 0.0-50.0 A (primary current measurement range) CT ratio: 1/1,000 Measurement accuracy: ±5% F.S. ±1 digit 	-						
Option input	Digital input	• Contact $ON: \leq 1 \text{ K}\Omega, \text{ OFF: } \geq 100 \text{ K}\Omega$ • Non contact residual voltage: $\leq 1.5 \text{ VDC} =$ leakage current: $\leq 0.1 \text{ mA}$ • Outflow current: $\approx 0.5 \text{ mA per input}$	-						
	Relay	250 VAC~ 3 A 1a, 30 VDC= 3 A 1a							
Control	SSR	12 VDC== ±3 V, ≤ 30 mA 22 VDC== ±3 V, ≤ 30 mA							
output Current		DC 4 - 20 mA or DC 0 - 20 mA (Load resistance	e: ≤ 500 Ω)						
Alarm output		250 VAC~ 3 A 1a	-						
RS485 Comm.		Modbus RTU							
Display type		None- parameter setting and monitoring is available at external devices							
Control type	Heating, Cooling Heating & Cooling	ON/OFF, P, PI, PD, PID Control							
Hysteres		1 to 100 (0.1 to 100) °C/°F							
	onal band (P)	0.1 to 999.9 °C/°F							
Integral t		0 to 9.999 sec							
	e time (D)	0 to 9,999 sec							
Control c		0.1 to 120.0 sec							
Manual r	eset	0.0 to 100.0 %							
Relay life	Mechanical	≥ 10,000,000 operations							
cycle	Electrical	\geq 100,000 operations (250 VAC \sim 3 A load resistance)							
Dielectric	: strength	Between input terminal and power terminal: 2,000 VAC \sim 50/60 Hz for 1 min							
Vibration	l.	0.75 mm amplitude at frequency of 5 to 55 Hz (for 1 min) in each X, Y, Z direction for 2 hours							
Insulatio	n resistance	100 MΩ (500 VDC== megger)							
Noise im		\pm 0.5 kV square shaped noise (pulse width 1							
Ambient temperature									
Ambient humidity		35 to 85%RH, storage: 35 to 85%RH (no freezing or condensation)							
Channel	insulation	Dielectric strength 1,000 VAC~							
Insulatio		Double insulation or reinforced insulation (mark: , dielectric strength between the measuring input part and the power part: 1 kV)							
Approval		C E e 📲 us 🕼 EAE							
Unit weig (package		• Basic module: $\approx 152 \text{ g} (\approx 217 \text{ g})$ • Expansion module: $\approx 143 \text{ g} (\approx 208 \text{ g})$ • State and the second secon							

Input Type and Using Range

The setting range of some parameters is limited when using the decimal point display.

Input typ	Input type		Display method	Using range (°C)			Using range (°F)			
	K (CA)	1	K (CA) .H	-200	to	1,350	-328	to	2,462	
	R (CA)	0.1	K (CA) .L	-200.0	to	1,350.0	-328.0	to	2462.0	
	J (IC)	1	J (IC) .H	-200	to	800	-328	to	1,472	
	J (IC)	0.1	J (IC) .L	-200.0	to	800.0	-328.0	to	1472.0	
	E (CR)	1	E (CR) .H	-200	to	800	-328	to	1,472	
	E (CR)	0.1	E (CR) .L	-200.0	to	800.0	-328.0	to	1,472.0	
	T (CC)	1	T (CC) .H	-200	to	400	-328	to	752	
	T (CC)	0.1	T (CC) .L	-200.0	to	400.0	-328.0	to	752.0	
The second second	B (PR)	1	B (PR)	0	to	1,800	32	to	3,272	
Thermo -couple	R (PR)	1	R (PR)	0	to	1,750	32	to	3,182	
-couple	S (PR)	1	S (PR)	0	to	1,750	32	to	3,182	
	N (NN)	1	N (NN)	-200	to	1,300	-328	to	2,372	
	C (TT) 01)	1	C (TT)	0	to	2,300	32	to	4,172	
	G (TT) 02)	1	G (TT)	0	to	2,300	32	to	4,172	
	L (IC)	1	L (IC) .H	-200	to	900	-328	to	1,652	
	L (IC)	0.1	L (IC) .L	-200.0	to	900.0	-328.0	to	1,652.0	
	U (CC)	1	U (CC) .H	-200	to	400	-328	to	752	
	0 (CC)	0.1	U (CC) .L	-200.0	to	400.0	-328.0	to	752.0	
	Platinel II	1	PLII	0	to	1,400	32	to	2,552	
	JPt100 Ω	1	JPt100.H	-200	to	650	-328	to	1,202	
RTD	JPt100 Ω	0.1	JPt100.L	-200.0	to	650.0	-328.0	to	1,202.0	
NID	DPt100 Ω	1	DPt100.H	-200	to	650	-328	to	1,202	
	DPt100 Ω	0.1	DPt100.L	-200.0	to	650.0	-328.0	to	1,202.0	

01) C (TT): Same as existing W5 (TT) type sensor 02) G (TT): Same as existing W (TT) type sensor

Measurement accuracy

Input type	Using temperature	Measurement accuracy
Thermo -couple	At room temperature (23 ±5 °C)	(PV ±0.5% or ±1 °C higher one) ±1-digit • Thermocouple K, J, T, N, E below -100 °C and L, U, PLII: ±2 °C ±1-digit • Thermocouple C, G and R, S below 200 °C: ±3 °C ±1-digit • Thermocouple B below 400°C: there is no accuracy standards
RTD	Out of room temperature range	$ \begin{array}{l} (PV\pm0.5\%\text{or}\pm2^\circ\text{C}\text{higher one})\pm1\text{-digit}\\ \cdotRTDCu50\Omega,DPt50\Omega;(PV\pm0.5\%\text{or}\pm3^\circ\text{C}\text{higher one})\pm1\text{-digit}\\ \cdotThermocoupleR,S,B,C,G,L,U;(PV\pm0.5\%\text{or}\pm5^\circ\text{C}\text{higher one})\\ \pm1\text{-digit}\\ \cdotThermocouple\text{below}\cdot100^\circ\text{C}:\pm5^\circ\text{C} \end{array}$

Communication Interface

RS485

Protocol	Modbus RTU
Application standard	EIA RS485 compliance with
Maximum connection	31 units (address: 01to31)
Synchronization type	Asynchronous
Connection type	Two-wire half duplex
Comm. effective range	≤ 800 m
Comm. speed	2,400 / 4,800 / 9,600 (default) / 19,200 / 38,400 (parameter)
Start bit	1 bit (fixed)
Data bit	8 bit (fixed)
Parity bit	None (default) , Odd, Even
Stop bit	1 bit, 2 bit (default)

When changing the setting value related to communication interface, reboot the device for normal operation.
 It is not allowed to set overlapping communication address at the same communication line.
 It is recommended to use Autonics communication converter. Please use twisted pair wire, which is suitable for RS485 communication.

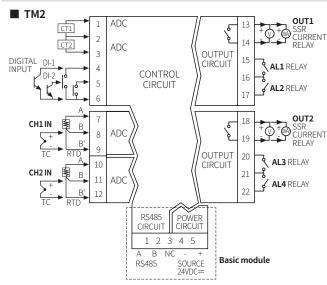
Address

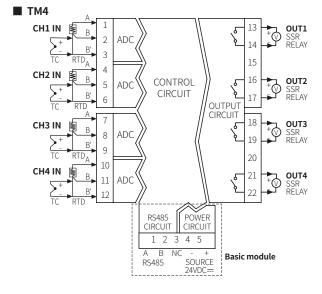
Set the communication address with the communication address setting switch (SW1, default: 1) and communication address group switch (SW2, default: +0).

• When setting as 0, it does not operate communication.

SW1		🔅														
SW2	0	1	2	3	4	5	6	7	8	9	А	В	С	D	E	F
+0+16	X	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15
+0+16	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31



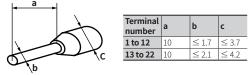




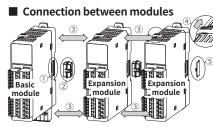
Crimp Terminal Specifications

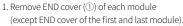
• Unit: mm, Use the crimp terminal of follow shape.

Wire ferrule



Installation Method





2. Insert side connector (2) and connect them tightly to 3 direction (max. 30 units).

- 3. Press lock switch (④) to lock direction.
- · Supply adequate power for power input specifications and overall capacity. (Max. power when connecting 31 modules:

31 units×5 W=155 W)

Mounting with bolts



1. Pull the rail lock at the top and bottom of the module to \bigcirc direction.

2. Insert M4 bolts to ② direction and fix it on rail lock. (Tightening torque: 0.5 to 0.9 N m)

Mounting on DIN rail

- Installation



1. Hang the top rail lock to DIN rail. 2. Push to ① direction 2 and press to ②

- Separation

1. Press the module to 1direction.

Connector Sensor

input

Power / Comm. Connector

[Basic module]

onnector

Control

output

connector

2. Keep it pressed and pull it to 2 direction.

direction.

Precautions • Install the module vertically.

• Use end plates (sold separately, not available from Autonics) to fix firmly.

Errors

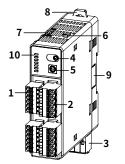
Indicator									
Name	Status	Color	Description	Troubleshooting					
PWR	ON	Red		When the error factor is					
CH□	Flash Red		Input > Input range, Input sensor is open or not connected	resolved, it automatically returns to normal operation.					

01) Cycle: 0.5 sec

Communication output, DAQMaster

Communication output (decimal)	DAQMaster	Description	Troubleshooting			
'31000'	Display 'OPEN'	Input sensor is open or not connected	When the error factor is			
'30000'	Display 'HHHH'	Input > Input range	resolved, it automatically returns to normal operation.			
'-30000'	Display 'LLLL'	Input < Input range				

Unit Descriptions



1. Sensor input connector

2. Control output connector

3. Power/Comm. Terminal (Basic module)

Refer to 'Connections' for the detail description about connector and terminal.

4. PC loader port

For serial communication between one module and PC to set parameter and monitoring by using communication converter.

5. Communication address setting switch (SW1) 6. Communication address group switch (SW2)

When setting the communication address over 16, select +16.

7. Lock switch

Used for fixing modules at top and bottom.

8. Rail lock

Used for installing at DIN rail or using bolts.

9. END cover

Remove it when connecting each module to connect an side connector for expansion. 10. Indicator

TM2

Status		Control	Auto	Alarm output					
	Initial power ON ⁰¹⁾		tuning ⁰²⁾	N.O.		N.C			
Indicator		ουιραι	tuning	OFF	ON	OFF	ON		
PWR (Green) 03)	ON	ON	ON						
CH1 (Red)	Flash (4,800 bps)	ON	Flash]-					
CH2 (Red)	Flash (9,600 bps)	ON	Flash	1					
AL1 (Yellow)	Flash (19,200 bps)	ON 04)	OFF	OFF	ON	OFF	ON		
AL2 (Yellow)	Flash (38,400 bps)	ON 05)	OFF	OFF	ON	OFF	ON		
AL3	-	-	OFF	OFF	ON	OFF	ON		
AL4	-	-	OFF	OFF	ON	OFF	ON		

TM4

Indicator	Initial power ON ⁰¹⁾	Control output	Auto tuning ⁰²⁾		
PWR (Green) 03)	ON	ON	ON		
CH1 (Red)	Flash (4,800 bps)	ON	Flash		
CH2 (Red)	Flash (9,600 bps)	ON	Flash		
CH3 (Red)	Flash (19,200 bps)	ON 04)	Flash		
CH4 (Red)	Flash (38,400 bps)	ON	OFF		
- (Yellow)	-	-	OFF		
- (Yellow)	-	-	OFF		

01) When power is supplied initially, the set communication speed LED flashes for 5 sec. 02) The auto tuning CH LED flashes for 1 sec in turn. 03) The PWR LED flashes during communication for 1 sec in turn.

(4) Turns ON when CH1 control method is heating & cooling control and cooling output occurs. (disable AL1 setting).
 (5) Turns ON when CH2 control method is heating & cooling control and cooling output occurs. (disable AL2 setting)