Dual Display PID Temperature Controllers

TCN Series

INSTRUCTION MANUAL

TCD210225AA

Autonics

Thank you for choosing our Autonics product.

Read and understand the instruction manual and manual thoroughly before using the product.

For your safety, read and follow the below safety considerations before using. For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

Keep this instruction manual in a place where you can find easily.

The specifications, dimensions, etc are subject to change without notice for product improvement Some models may be discontinued without notice.

Follow Autonics website for the latest information.

Safety Considerations

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- A symbol indicates caution due to special circumstances in which hazards may occur.

★ Warning Failure to follow instructions may result in serious injury or death

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss.(e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.)
- Failure to follow this instruction may result in personal injury, economic loss or fire. 02. Do not use the unit in the place where flammable/explosive/corrosive gas,
- high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.

Failure to follow this instruction may result in explosion or fire.

- 03. Install on a device panel to use.
- Failure to follow this instruction may result in fire or electric shock.
- 04. Do not connect, repair, or inspect the unit while connected to a power

Failure to follow this instruction may result in fire or electric shock.

- 05. Check 'Connections' before wiring.
- Failure to follow this instruction may result in fire.
- 06. Do not disassemble or modify the unit. Failure to follow this instruction may result in fire or electric shock.

- ↑ Caution Failure to follow instructions may result in injury or product damage 01. When connecting the power input and relay output, use AWG 20 (0.50 mm²)
- to 0.90 N m. When connecting the sensor input and communication cable without $\label{eq:connection} % \[\begin{array}{c} (x,y) & (x,y) \\ (x,y) & (x,$ dedicated cable, use AWG 28 to 16 cable and tighten the terminal screw with

cable or over, and tighten the terminal screw with a tightening torque of 0.74

- a tightening torque of 0.74 to 0.90 N m. Failure to follow this instruction may result in fire or malfunction due to contact
- 02. Use the unit within the rated specifications.
- Failure to follow this instruction may result in fire or product damage
- 03. Use a dry cloth to clean the unit, and do not use water or organic solvent. Failure to follow this instruction may result in fire or electric shock.
- 04. Keep the product away from metal chip, dust, and wire residue which flow into the unit.

Failure to follow this instruction may result in fire or product damage.

Cautions during Use

- Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected
- Check the polarity of the terminals before wiring the temperature sensor.
 For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length. For thermocouple (TC) temperature sensor, use the designated compensation wire for extending wire.
- Keep away from high voltage lines or power lines to prevent inductive noise. In case installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line. Do not use near the equipment which generates strong magnetic force or high frequency noise.

 Install a power switch or circuit breaker in the easily accessible place for supplying or
- disconnecting the power
- Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature
- When changing the input sensor, turn off the power first before changing. After
- changing the input sensor, modify the value of the corresponding parameter • 24 VAC~, 24-48 VDC= power supply should be insulated and limited voltage/current
- or Class 2, SELV power supply device. Make a required space around the unit for radiation of heat. For accurate temperature
- measurement, warm up the unit over 20 min after turning on the power. Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.
- · Do not wire to terminals which are not used.
- This unit may be used in the following environments
- Indoors (in the environment condition rated in 'Specifications')
- Altitude Max. 2,000 m
- Pollution degree 2
- Installation category II

Ordering Information

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website



Size

S: DIN W $48 \times H 48 \text{ mm}$

Wiring type No mark: Bolt

M: DIN W 72 × H 72 mm H: DIN W 48 × H 96 mm

L: DIN W $96 \times H 96 \text{ mm}$

Power supply

2: 24 VAC~ 50/60 Hz, 24-48 VDC= 4: 100-240 VAC ~ 50/60 Hz

Product Components

Product

P: Connector plug connection

· Instruction manual

• Bracket

Sold Separately

• Terminal protection cover: RSA / RMA / RHA / RLA Cover

Specifications

Series		TCN4□-22□-□	TCN4□-24□-□					
Power su	upply	24 VAC~ 50/60 Hz ±10% 24 - 48 VDC== ±10%	100 - 240 VAC∼ 50/60 Hz ±10%					
Power co	onsumption	$AC: \le 5 \text{ VA, DC: } \le 3 \text{ W}$ $\le 5 \text{ VA}$						
Samplin	g period	100 ms						
Input sp	ecification	Refer to 'Input Type and Using Ran	ge.					
Control	Relay	250 VAC∼ 3A, 30 VDC== 3A, 1a						
output	SSR	12 VDC=±2 V, ≤ 20 mA						
Alarm oı	ıtput	250 VAC∼ 1 A 1a						
Display t	уре	7 Segment (red, green), LED type						
Control type	Heating, Cooling	ON/OFF, P, PI, PD, PID Control						
Hysteres	sis	1 to 100 (0.1 to 50.0) °C/°F						
Proporti (P)	onal band	0.1 to 999.9 °C/°F						
Integral	time (I)	0 to 9,999 sec						
Derivativ	ve time (D)	0 to 9,999 sec						
Control cycle (T)		0.5 to 120.0 sec						
Manualı	reset	0.0 to 100.0%						
Relay	Mechanical	≥ 5,000,000 operations						
life cycle	Electrical	OUT1/2: \geq 200,000 operations (load resistance: 250 VAC \sim 3 A) AL1/2: \geq 300,000 operations (load resistance: 250 VAC \sim 1 A)						
Dielectri	c strength	Between input terminal and power terminal: 1,000 VAC \sim 50/60 Hz for 1 min Between input terminal: 2,000 VAC \sim 50/ $^{\circ}$ min						
Vibratio	n	0.75 mm amplitude at frequency of 5 to 55 Hz (for 1 min) in each X, Y, Z direction for 2 hours						
Insulation resistance		≥ 100 MΩ (500 VDC== megger)						
Noise im	munity	$\pm 2\text{kV}$ square shaped noise (pulse width: $1\mu\text{s})$ by noise simulator R-phase, S-phase						
Memory	retention	pprox 10 years (non-volatile semiconductor memory type)						
Ambient tempera		-10 to 50 °C, storage: -20 to 60 °C (no freezing or condensation)						
Ambient	humidity	35 to 85%RH, storage: 35 to 85%RH (no freezing or condensation)						
Insulatio	on type	Mark: □, double or reinforced insulation (dielectric strength between the measuring input part and the power part: 1 kV) Mark: □, double or reinforced insulation (dielectric strength between the measuring input pa and the power part: 2 kV)						
Approva	ι							
Unit wei		• TCN4S: ≈ 100 g (≈ 147 g) • TCN4H: ≈ 124 g (≈ 194 g)	• TCN4M: ≈ 133 g (≈ 203 g) • TCN4I: ≈ 179 g (≈ 275 g)					
(раскадец)		• TCN4H: ≈ 124 g (≈ 194 g)	• TCN4L: ≈ 179 g (≈ 275 g)					

Input Type and Using Range

The setting range of some parameters is limited when using the decimal point display.

Input type		Decimal point	Display	Using ran	ge (°C)	Using r	ange (°F)
	K (CA)	1	F E WH	-50 to	1,200	-58	to 2,192
		0.1	F.C. R.L	-50.0 to	999.9	-58.0	to 999.9
	J (IC)	1	JI C.H	-30 to	800	-22	to 1,472
		0.1	JI C.L	-30.0 to	0.008	-22.0	to 999.9
Thermo	L (IC)	1	LI C.H	-40 to	800	-40	to 1,472
-couple		0.1	LI C.L	-40.0 to	0.008	-40.0	to 999.9
	T (CC)	1	Ł ℂ ℂ.H	-50 to	400	-58	to 752
		0.1	E C C.L	-50.0 to	400.0	-58.0	to 752.0
	R (PR)	1	- ۹ -	0 to	1,700	32	to 3,092
	S (PR)	1	5Pr	0 to	1,700	32	to 3,092
	Cu50 Ω	1	C U 5.H	-50 to	200	-58	to 392
DTD		0.1	C U 5.L	-50.0 to	200.0	-58.0	to 392.0
RTD	DPt100 Ω	1	dPE.H	-100 to	400	-148	to 752
	DE(100 7)	0.1	dPE.L	-100.0 to	400.0	-148.0	to 752.0

■ Display accuracy

Input type	Using temperature	Display accuracy
Thermocouple	At room temperature (23°C ±5°C)	$\label{eq:continuous} \begin{array}{l} (\text{PV}\pm 0.5\% \text{ or} \pm 1^{\circ}\text{C higher one}) \pm 1\text{-digit} \\ \bullet \text{ Thermocouple R, S below 200^{\circ}\text{C}:} \\ (\text{PV}\pm 0.5\% \text{ or} \pm 3^{\circ}\text{C higher one}) \pm 1\text{-digit} \\ \text{Over 200^{\circ}\text{C}:} \\ (\text{PV}\pm 0.5\% \text{ or} \pm 2^{\circ}\text{C higher one}) \pm 1\text{-digit} \\ \bullet \text{ Thermocouple L, RTD Cu50} \ \Omega:} \\ (\text{PV}\pm 0.5\% \text{ or} \pm 2^{\circ}\text{C higher one}) \pm 1\text{-digit} \\ \end{array}$
RTD	Out of room temperature range	(PV ±0.5% or ±2 °C higher one) ±1-digit • Thermocouple R, S below 200 °C: (PV ±1.0% or ±6 °C higher one) ±1digit Over 200 °C: (PV ±0.5% or ±5 °C higher one) ±1digit • Thermocouple L, RTD Cu50 Ω: (PV ±0.5% or ±3 °C higher one) ±1digit

Unit Descriptions



1. PV Display part (red)

• RUN mode: Displays PV (Present value)

• Setting mode: Displays parameter name

2. SV Display part (green)

• RUN mode: Displays SV (Setting value)

• Setting mode: Displays parameter setting value

3. Indicator

I	Display	Name	Description	
1	AL1/2	Alarm output	Turns ON when the alarm output is ON.	
(DUT	Control output	Turns ON when control output is ON • CYCLE/PHASE control of SSR drive output: Turns ON when MV is over 3.0% [AC power model]	
-	AT	Auto tuning	Flashes during auto tuning every 1 sec	
	°C, %, °F	Unit	Displays selected unit (parameter).	

LLLL Flashes when PV is lower than input range.

4. Input key Display Name [MODE] Mode key Setting value $[\blacktriangleleft], [\blacktriangledown], [\blacktriangle]$

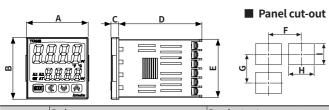
range, this display disappears.

Errors Display Description Troubleshooting Flashes when input sensor is disconnected or sensor is not connected. Check input sensor status. HHHH Flashes when PV is higher than input range. When input is within the rated input

[•] For TCN4S- \square -P, add $\pm 1^{\circ}$ C by accuracy standard. • If the input specification is set to 'decimal point 0.1' display, add $\pm 1^{\circ}$ C by accuracy standard.

Dimensions

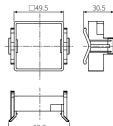
- Unit: mm, For the detailed drawings, follow the Autonics website.
- Below is based on TCN4S Series .



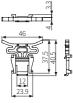
	Body					Panel cut-out			
	Α	В	С	D	E	F	G	Н	I
TCN4S	48	48	6	64.5	44.8	≥ 65	≥ 65	45 0.5	45 ^{+0.5}
TCN4S-□-P	48	48	7.7	65.8	44.8	≥ 65	≥ 65	45 ^{+0.5}	45 ^{+0.5}
TCN4M	72	72	6	64.5	67.5	≥ 90	≥ 90	68 ^{+0.7}	68 ^{+0.7}
TCN4H	48	96	6	64.5	91.5	≥ 65	≥ 115	45 ^{+0.6}	92 0 0
TCN4L	96	96	6	64.5	91.5	≥ 115	≥ 115	92 0 0	92 0 0

■ Bracket

TCN4S

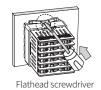


Other series

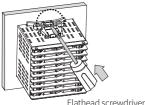


Installation Method

■ TCN4S



Other series



Fork crimp terminal Round crimp terminal

Insert the unit into a panel, fasten the bracket by pushing with a flathead screwdriver.

Crimp Terminal Specifications

• Unit: mm, Use the crimp terminal of follow shape.





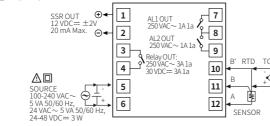


Wire ferrule

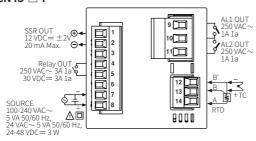
1 to 8 $\leq 1.7 \leq 3.7$ **9 to 11** $| 6 \text{ to } 8 | \leq 2.1 | \leq 4.2$ **12 to 14** 6 to 8 \leq 1.5 \leq 3.5

Connections

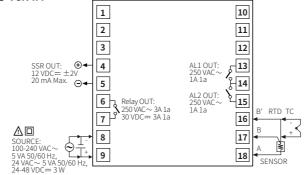
■ TCN4S



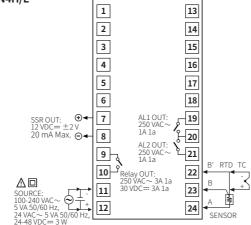
■ TCN4S-□-P



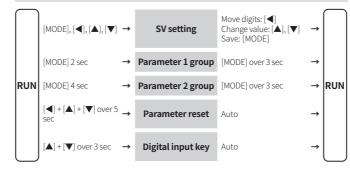
■ TCN4M



■ TCN4H/L



Mode Setting



Parameter Setting

- Some parameters are activated/deactivated depending on the model or setting of other parameters. Refer to the description of each item.
- $\bullet \mbox{ The setting range in parentheses is for using the decimal point display in the input} \\$ specification.
- If there is no key input for more than 30 seconds in each parameter, it returns to RUN
- When pressing the [MODE] key within 1 second after returning to the operation mode from the parameter group, it will enter the parameter group before returning.
- \bullet [MODE] key: Saves the current parameter setting value and moves to the next narameter
- [◀] key: Checks the fixed item / Moves the row when changing the set value
- [▲], [▼] keys: Selects the parameter / Changes the set value
- Recommended parameter setting sequence: Parameter 2 group → Parameter 1 group \rightarrow SV setting mode

■ Parameter 1 group

Par	ameter	Display	Default	Setting range	Condition
1-1	AL1 alarm temperature	ALI	1250	Deviation alarm: -F.S. to F.S. °C/°F	2-12/14 alarm
1-2	AL2 alarm temperature	AL 2	1250	Absolute value alarm: Within input range	operation: AM1 to AM6
1-3	Auto tuning	ЯŁ	oFF	OFF: Stop, ON: Execution	
1-4	Proportional band	Р	0 10.0	0.1 to 999.9 °C/°F	2-8 Control
1-5	Integral time	;	0000	0 (OFF) to 9999 sec	type: PID
1-6	Derivative time	В	0000	0 (OFF) to 9999 sec	
1-7	Manual reset	r E S E	050.0	0.0 to 100.0%	2-8 Control type: PID & 1-5 Integral time: 0
1-8	Hysteresis	H 5	002	1 to 100 (0.1 to 50.0) °C/°F	2-8 Control type: ONOF

■ Parameter 2 group

Para	meter	Display	Default	Setting range	Condition		
2-1	Input specification ⁰¹⁾	In-E	E C B'H	Refer to 'Input Type and Using Range'.	-		
2-2	Temperature unit 01)	Unit	٥.	°C, °F	-		
2-3	Input correction	In-b	0000	-999 to 999 (-199.9 to 999.9) °C/°F	-		
2-4	Input digital filter	ñ R u.F	000.1	0.1 to 120.0 sec	-		
2-5	SV low limit ⁰²⁾	L-5u	-50	Within 2-1 Input specification Input	-		
2-6	SV high limit ⁰²⁾	H-5u	1200	range, L-SV ≤ H-SV - 1-digit °C/°F H-SV ≥ L-SV + 1-digit °C/°F	-		
2-7	Control output mode ⁽¹³⁾	0-FE	неяь	HEAT: Heating, COOL: Cooling	-		
2-8	Control type 04)	[-ñd	PId	PID, ONOF: ON/OFF	-		
2-9	Control output	oUt	rLY	RLY: relay, SSR	-		
2-10	SSR drive output type	55r.ñ	Stnd	[AC model] STND: standard, CYCL: cycle, PHAS: phase	2-9 Control output: SSR		
2-11	Control cycle	E	2 0.0	0.5 to 120.0 sec	2-9 Control output: RLY 2-10 SSR drive output type: STND		
			2.0		2-9 Control output: SSR 2-10 SSR drive output type: STND		
2-12	AL1 alarm operation	86 L 1 86 L8		AM0: Off AM1: Deviation high limit alarm AM2: Deviation low limit alarm AM3: Deviation low limit alarm AM3: Deviation high, low limit alarm AM4: Deviation high, low reverse alarm AM5: Absolute value high limit alarm AM6: Absolute value low limit alarm SBA: Sensor break alarm LBA: Loop break alarm (LBA)	-		
2-13	AL1 alarm option	חנייו				A: Standard alarm D: Alarm latch and standby sequence 1 E: Standby sequence 1 E: Standby sequence 2 • Enter to option setting: Press [◀] key in 2-12 Al-1 alarm operation.	-
2 14	AL2 alarm			III Z ZZ Z Z GOTT OPCIOLOSII			
	AL2 alarm	AL-5	A y r	Same as 2-12/13 AL1 alarm operation/option	-		
	Alarm output hysteresis	ЯНЧ5	001	1 to 100 (0.1 to 50.0) °C/°F	2-12/14 AL1/2 alarm operation: AM1 to 6		
2-17	LBA time	LBRE	0000	0 (OFF) to 9999 sec or auto (auto tunning)	2-12/14 AL1/2 alarm operation: LBA		
2-18	LBA band	L b R.b	0002	0 (OFF) to 999 (0.0 to 999.9) °C/°F or auto (auto tunning)	2-12/14 AL1/2 alarm operation: LBA & 2-18 LBA time: > 0		
2-19	Digital input key	91 - 5	StoP	STOP: Stop control output, AL.RE: Alarm reset, AT*: Auto tuning execution, OFF	*2-8 Control type: PID		
2 20	Sensor error			0.0: OFF, 100.0: ON	2-8 Control type: ONOF		
2-20	MV	Er.ñu	0.0 to 100.0%		2-8 Control type: PID		
2-21	Lock	LoC	oFF	OFF LOC1: Parameter 2 group lock LOC2: Parameter 1/2 group lock LOC3: Parameter 1/2 group, SV setting lock	-		

18. Bansong-ro 513Beon-gil, Haeundae-gu, Busan, Republic of Korea, 48002 www.autonics.com | +82-2-2048-1577 | sales@autonics.com



⁻ Parameter 1 group: AL1/2 alarm temperature
- Parameter 1 group: AL1/2 alarm temperature
- Parameter 2 group: Input correction, SV high/low limit, Alarm output hysteresis, LBA time, LBA band
- SV setting mode: SV

⁰²⁾ If SV is lower than low limit or higher than high limit when the value is changed, SV is changed to the low/high

If 2-1 Input specification is changed, the value is changed to Min./Max. value of Input specification.

⁰³⁾ When the setting value is changed, setting value of 2-20 Sensor error MV is initialized to 0.0 (OFF).

04) When changing the value from PID to ONOF, each value of following parameter is changed.

2-19 Digital input key: OFF, 2-20 Sensor error MV: 0.0 (when setting value is lower than 100.0)