Autonics TCD210147AD

3-Phase Slim Power Controllers



SPR3 Series

PRODUCT MANUAL

For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

The specifications, dimensions, etc. are subject to change without notice for product improvement. Some models may be discontinued without notice.

Features

- · Slim and elegant design
- LED display allows real-time monitoring of control input, load voltage, load current, load power, load resistance, and heat-sink temperature
- Stable control with feedback control (constant current, constant voltage, constant power)
- Communication output models available: RS485 (Modbus RTU)
- Parameter configuration via PCs (RS485): Free device management software (DAQMaster)
- · Various alarm functions (alarm output): overcurrent, overvoltage, heater disconnection, fuse break, heat-sink overheat, diode (SCR) error
- Easy installation with mounting brackets
- Easy fuse replacement and maintenance
- · Inter phase insulating barrier included
- · High performance SCR (IXYS) diode

Safety Considerations

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- ▲ symbol indicates caution due to special circumstances in which hazards may occur.

⚠ Warning Failure to follow instructions may result in serious injury or death.

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss.(e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime / disaster prevention devices, etc.) Failure to follow this instruction may result in personal injury, economic loss or fire.

 O2. Do not use the unit in the place where flammable / explosive / corrosive gas,
- high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.

- Failure to follow this instruction may result in explosion or fire. **03. Install on the device panel, and ground to the bolt for grounding separately.**Failure to follow this instruction may result in fire or electric shock.
- 04. Do not connect, repair, or inspect the unit while connected to a power source. ailure to follow this instruction may result in fire or electric shock
- 05. Check 'Connections' before wiring.

Failure to follow this instruction may result in fire. **06. Do not disassemble or modify the unit.**

Failure to follow this instruction may result in fire or electric shock.

⚠ Caution Failure to follow instructions may result in injury or product damage.

 ${\bf 01.}\ Use the unit within the rated specifications.$

ailure to follow this instruction may result in fire or product damage

- 02. Use a dry cloth to clean the unit, and do not use water or organic solvent. Failure to follow this instruction may result in fire or electric show
- 03. Keep the product away from metal chip, dust, and wire residue which flow into the unit.

Failure to follow this instruction may result in fire or product damage

04. Since leakage current still flows right after turning off the power or in the output OFF status, do not touch the load terminal.

Failure to follow this instruction may result in electric shock

Cautions during Use

- Follow instructions in 'Cautions during Use'.
- Otherwise, it may cause unexpected accidents. Use the product, after 3 sec of supplying power.
- Before use, set the mode and function according to the specification. Especially, be cautious that the product does not operate when output control adjuster (OUT ADJ) is set to 0 %. Since changing the mode / parameter during operation may result in malfunction, set the mode and function after disconnecting load output.

 Re-supply the power to the unit after the unit is discharged completely. Failure to follow this instruction may result in malfunction.
- To ensure the reliability of the product, install the product on the panel or metal surface vertically to the ground.
 Install the unit in the well ventilated place.
- While supplying power to the load or right after turning off the power of the load, do not touch the body and heat sink. Failure to follow this instruction may result in a burn due to the high temperature.
- Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power.

 Do not wire to terminals which are not used.

 Use twisted pair wire for communication line.

- · Since inter element can be damaged when using with coil load, inductive load, etc., the inrush current must be under the rated load current.

 Do not use near the equipment which generates strong magnetic force or high

- This unit may be used in the following environments.
 Indoors (in the environment condition rated in 'Specifications')
 - Altitude max. 2,000 m
- Pollution degree 2 Installation category III

Ordering Information

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website.

3

SPR Rated load voltage

1: 110 VAC~ 2: 220 VAC~

3: 380 VAC.~

4: 440 VAC

2 Rated load current Number: Rated load current (unit: A)

0 0

Option output

N: Alarm output

T: Alarm output + RS485 comm. output

Feedback control

N: Normal control

F: Normal, feedback control (constant $\dot{\text{current}\,/\,\text{constant}\,\text{voltage}\,/\,\text{constant}}$ power)

6 Fuse

N: None

F: Supports fuse

Product Components

- Product
- 11-pin connector \times 1
- · Instruction manual
- Insulating barrier \times 4

Manual

For proper use of the product, refer to the manuals and be sure to follow the safety considerations in the manuals.

Download the manuals from the Autonics website.

Software

Download the installation file and the manuals from the Autonics website.

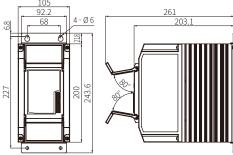
DAQMaster

It is the comprehensive device management program for Autonics' products, providing parameter setting, monitoring and data management.

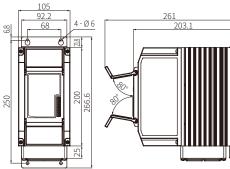
Dimensions

• Unit: mm, For the detailed drawings, follow the Autonics website.

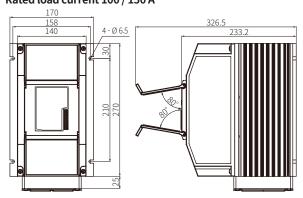
■ Rated load current 25 / 35 / 50 A



■ Rated load current 70 A



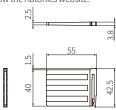
■ Rated load current 100 / 150 A

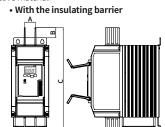


Insulating Barrier

It is recommended to use the included interphase barriers for insulation between phases and reduce influence from conductive material.

· Unit: mm, For the detailed drawings, follow the Autonics website.





Rated load current	Α	В	С
25 / 35 / 50 A	30	28.2	300
70 A	30	28.2	300
100 / 150 A	40.5	50	370

Cautions during Installation

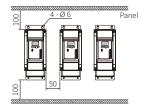
Migh Temperature Caution

While supplying power to the load or right after turning off the power of the load, do not touch the body and heatsink.
Failure to follow this instruction may result in a burn due to the high temperature.

■ Mount space

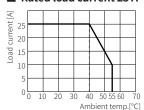
- Unit: mm
- When installing multiple power controllers, keep space between power controllers for heat radiation

Horizontal: \geq 50 mm, vertical: \geq 100 mm

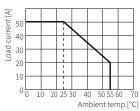


Derating Curve

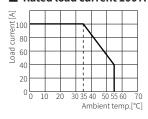
Rated load current 25 A



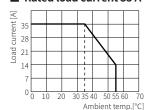
■ Rated load current 50 A



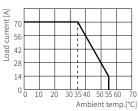
■ Rated load current 100 A



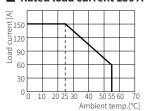
Rated load current 35 A



■ Rated load current 70 A



■ Rated load current 150 A



Specifications

	1		1		
Model	SPR3-1	SPR3-2	SPR3-3	SPR3-4	
Control phase	3-Phase				
Rated load voltage	110 VAC~ 50 / 60 Hz	220 VAC~ 50 / 60 Hz	380 VAC~ 50 / 60 Hz	440 VAC~ 50 / 60 Hz	
Rated load current	25 / 35 / 50 / 70 /	100 / 150 A			
Display method	3-digit 7segment	LED			
Indicators	Operation / manual control indicator (green) Alarm / output / unit (V, A) indicator (red)				
Auto control input	Current: DC 4 - 20 mA, voltage: 1 - 5 VDC=-, contact (non-voltage): ON / OFF, contact (voltage): 5 - 12 VDC=-, communication: RS485				
Manual control input	External adjuster (10 kΩ), output control adjuster (OUT ADJ)				
Digital input (DI)	RUN / STOP sele	ctable, AUTO / MAI	N selectable, RESE	Т	
Alarm output	250 VAC~ 3 A, 30 VDC= 3 A, 1c resistance load				
RS485 comm. output	Modbus RTU method				
Cooling method	Rated load current 25 / 35 / 50 A: natural cooling Rated load current 70 / 100 / 150 A: forced air cooling (with cooling fan)				
Unit weight (packaged)	Rated load current 25 / 35 / 50 A: \approx 4.1 kg (\approx 4.9 kg) Rated load current 70 A: \approx 4.2 kg (\approx 5 kg) Rated load current 100 / 150 A: \approx 8.7 kg (\approx 9.7 kg)				
Approval	(€				

Control method	Phase control	Cycle control	ON/OFF control	
Control mode	Normal / constant current feedback / constant voltage feedback / constant power feedback	Fixed cycle	-	
Applied load Resistance load, inductive load		Resistance load	Resistance load, inductive load	
Output range	0 to 98 %	0 to 100 %	0 / 100 %	
Phase control output accuracy	• Normal control: within \pm 10 % F.S. of rated load voltage • Constant current feedback control: within \pm 3 % F.S. of rated load current • Constant voltage feedback control: within \pm 3 % F.S. of rated load voltage • Constant power feedback control: within \pm 3 % F.S. of rated load power			
Power supply	100 - 240 VAC a. +10 % 50 / 60 Hz			

Power supply	100 - 240 VAC∼ ±10 % 50 / 60 Hz
- '''	
Min. load current	1 A
Power consumption	Rated load current 25 / 35 / 50 A: \leq 14 VA Rated load current 70 A: \leq 22 VA Rated load current 100 / 150 A: \leq 32 VA
Insulation resistance	≥ 200 MΩ (500 VDC== megger)
Dielectric strength	Between input and power terminal: 2,000 VAC \sim 50 / 60 Hz for 1 min
Output leakage currents	≤ 10 mArms
Noise immunity	±2 kV square wave noise (pulse width: 1 μs) by the noise simulator
Memory retention	≈ 10 years (when using non-volatile semiconductor memory type)
Vibration	0.75 mm double amplitude at frequency of 5 to 55 Hz (for 1 min) in each X, Y, Z direction for 2 hours
Vibration (malfunction)	0.5 mm double amplitude at frequency of 5 to 55 Hz (for 1 min) in each X, Y, Z direction for 10 min
Ambient temp.	-10 to 55 °C, storage: -20 to 80 °C (no freezing or condensation)
Ambient humi.	35 to 85 %RH, storage: 35 to 85 %RH (no freezing or condensation)

Communication Interface

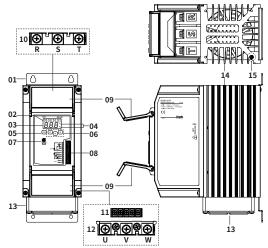
■ RS485

Comm. protocol	Modbus RTU
Application standard	Compliance with EIA RS485
Max. connection	31-unit (address: 01 to 99)
Comm. synchronous method	Asynchronous
Comm. method	2-wire half duplex
Comm. distance	≤ 800 m
Comm. speed	2,400 / 4,800 / 9,600 / 19,200 / 38,400 bps
Comm. response time	5 to 99 ms (default: 20 ms)
Start bit	1-bit (fixed)
Data bit	8-bit (fixed)
Parity bit	None, Even, Odd
Stop bit	1-bit, 2-bit

Load Output Formula

Туре	Input		Formula	
		DC 4 - 20 mA	Load output [%]	
Auto Voltag	Voltage	1-5VDC==	= Control input [%] × output slope [%]	
RS485 communication		ommunication	Load output [%] = RS485 [%]	
		Output control adjuster (OUT ADJ)	Load output [%] = output control adjuster [%]	
Manual	N) control Output control		Load output [%] = external adjuster [%]	
(MAN) control			Load output [%] = output control adjuster [%] × External adjuster [%]	

Unit Descriptions



01. Bracket [except rated load current 100 / 150 A model]

Indicat	tor	Function				
RUN Operation indicator (green)		Turns on in the RUN mode.				
MAN Manual control indicator (green)		Turns on when adjusting load output in the manual control mode.				
ALM Alarm indicator (red)		Flashes in alarming status.				
OUT Output indicator (red)		Turns on when load control outputs.				

03. Display part

RUN mode: Displays depending the front display setting Setting mode: Displays parameter and setting value

04. Unit indicator (V, A)

Dependent on the display setting

p					
Display setting	V	Α			
Resistance and input	OFF	OFF			
Voltage	ON	OFF			
Current	OFF	ON			
Power	ON	ON			

05. [MODE] key

Enters parameter group, returns to RUN mode, moves parameters, and saves the

setting value. **06.** [◀], [▼], [▲] key

Enters SV setting mode and move digits.

07. Output control adjuster (OUT ADJ)

Adjusts output from 0 to 100% in manual

08. Control input / comm. output terminal (11-pin connector terminal)

09. Terminal protection cover

10. R, S, T load input terminal

11. Alarm output / power input terminal 12. U, V, W load output terminal

13. Cooling fan

[Rated load current 70 / 100 / 150 A model]

14. Heatsink

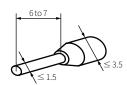
Rated load current 100 / 150 A models have left / right mounting holes.

15. Bolt for grounding (M4)

Cautions during Wiring

■ Control input / comm. output terminal (11-pin connector)

• Unit: mm, Use penhole terminals of size specified below.



■ Alarm output / power input & U, V, W load output terminal

• Unit: mm, Use crimp terminals of size specified below.



Rated load current Spec		Alarm output / power input	Load input / output
25/35/50/	а	≥ 3.0	≥ 6.0
70 A	b	≤ 6.0	≤ 16.0
100 / 150 A	а	≥ 3.0	≥ 8.0
100 / 150 A	b	≤ 6.0	≤ 26.0

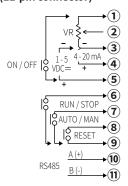
 \bullet Cable / screw / tightening torque spec. is different depending on the load current. Be sure to the below before connection.

Rated load current	Spec.	Alarm output / power input	Load input / output
	Cable	AWG 18 to 14	AWG 13 to 4
25 / 35 / 50 / 70 A	Screw	M3	M6
23/33/30/10A	Tightening torque	0.5 N m	5.5 to 6.0 N m
	Cable	AWG 18 to 14	AWG 4 to 2 / 0
100 / 150 A	Screw	M3	M8
	Tightening torque	0.5 N m	6.5 to 7.0 N m

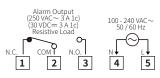
Connections

• Terminal configuration by model may differ depending on the supported spec.

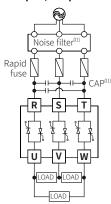
■ Control input / comm. output terminal (11-pin connector)



■ Alarm output / power input terminal



■ Load input / output terminal



01) When connecting noise filter and capacitor, it is appropriate for EMC. [CAP]

Rated load voltage 110 / 220 VAC~ : 1 μF / 250 VAC ~

Rated load voltage 380 / 440 VAC~ : 0.47 µF / 500 VAC~

Alarm

- Supported alarms are different depending on the model.
- When several alarms occur at same time, the highest priority error is displayed based

Duit a uite .	T	Diamle	Operation		Al	Madal	
Priority	Type	Display	Alarm	Output	Alarm release	Model	
1	SCR error	SEr				Feedback control	
2	Over current	o-E		Output		Feedback control	
4	Heatsink over heat	ŁEń	• Error	stops. (SCR OFF)	Re-supply power.	Normal / Feedback control	
5	Over voltage	o-u	display flashes.		RESET input Switch to stop		
7	Load unbalance	UL	Alarm indicator (ALM) flashes. Alarm	Normal operation / Output stops. (SCR OFF)	(STOP) mode.	Feedback control	
3	Fuse break	F U S	output turns ON	Output	Automatically	Normal /	
8	Frequency error	Fr9		stops. (SCR OFF) Normal operation		cleared when returning within	Feedback control
6	Heater break	Н-Ь			the setting range	Feedback control	

SCR error alarm

Even though output is 0 %, if the current of 10 % or more of the rated load current flows for over 3 sec continuously, SCR error alarm occurs.

Over current alarm

This function protects the load from over current. If the current flows over the P2-7 over current alarm value and P2-8 over current alarm delay time, over current alarm occurs.

· Heatsink over heat alarm

When the temperature of a heatsink is over 85 °C, heatsink over heat alarm occurs.

 Over voltage alarm
 This function protects the load from over voltage. If the current flows over the P2-9 over
 voltage alarm value and P2-10 over voltage alarm delay time, over voltage alarm occurs.

Load unbalance alarm

If the current of U, V, W is [load unbalance value ≥ P2-13 load unbalance alarm value], the alarm occurs.

When the alarm occurs, the load output operates as according to the set of P2-14 output

when load unbalance alarm occurs. \rightarrow ON: normal operation, OFF: output stops (SCR OFF)

Load unbalance value (A) = I_{max} - I_{min} (I_{max} : maximum phase load current value, I_{min} : minimum phase load current value) E.g.) R phase: 7 A, S phase: 2 A, T phase: 3 A, P2-13 load unbalance alarm value: 2 A Load unbalance value = 7 - 2 = 5 A

Load unbalance value > P2-13 load unbalance alarm value and the alarm occurs.

Fuse break alarm

When breaking fuse, not suppling load power, breaking load (single load), fuse brake alarm occurs. In the case of normal control model, real-time fuse break alarm is not available during output, and fuse break alarm operates at 0 % output such as RESET.

Heater break alarm

Comparing the full load resistance value and the current load resistance value, if the current load resistivity is maintained under the P2-12 heater break alarm value for over 3 se continuously, heater break alarm occurs. This alarm operates when control output is over 10 % and load current is over 10 % of the rated current. Output does not stop and operates normally

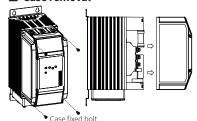
Full load resistance value \times 100 Current load resistance (%) = Current load resistance value

Frequency error alarm

When the load power frequency is out of the specification, frequency error alarm occurs.

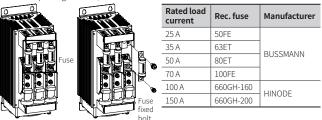
Replacement of Fuse

Case removal



Replacement of fuse

- Fuse none model is not equipped with a rapid fuse inside. Install the suitable fuse for rated load current of the model separately.
- \bullet The performance of the product is guaranteed only when using the fuse provided by us. For replacing the fuse, use the recommended fuse



■ Bolt specification

Rated load current	Case fixed bolt	Fuse fixed bolt	
25 / 35 / 50 / 70 A	M3	M6	
100 A	M4	Top: M8 Bottom: M6	
150 A	M4	M8	

Mode Setting

	[MODE]	\rightarrow	Monitoring group	[MODE] 3 sec	\rightarrow	
	[MODE] 2 sec	\rightarrow	Parameter 1 group	[MODE] 3 sec	\rightarrow	
	[MODE] 4 sec	\rightarrow	Parameter 2 group	[MODE] 3 sec	\rightarrow	
RUN	[◄ + ▲ + ▼] 5 sec	\rightarrow	Parameter reset	[MODE]	\rightarrow	RUN
	6 - 9 terminal external contact	\rightarrow	RUN / STOP	Auto	\rightarrow	
	7 - 9 terminal external contact	\rightarrow	Auto / Manual control	Auto	\rightarrow	
	[▲+▼] 2 sec or 8 - 9 terminal	\rightarrow	Reset ⁰¹⁾	Auto	\rightarrow	

01) In the event of system anomalies and alarms, RESET input restarts the power controller. (parameters are not

Parameter Setting

- Some parameters are activated / deactivated depending on the model or setting of other parameters. Refer to the description of each parameter.
- If any key is not entered for 30 sec in each parameter, it returns to RUN mode.
- [MODE] key: Saves current setting value and moves to the next parameter.
 [◄] key: Changes setting digits.
- [▲], [▼] key: Changes setting values.

■ Monitoring group

Param	eter	Display	Display range								
M1-1	Monitoring value	l n	0 to 100 %								
M1-2	U-V line load voltage value	U-u	re 11 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1								
M1-3	V-W line load voltage value	u - <u>u</u>	[Feedback control model] 0 to rated voltage range, V								
M1-4	W-U line load voltage value	2-0	o to rated voltage range, v								
M1-5	U-phase load current value	U-A	(e								
M1-6	V-phase load current value	u-A	[Feedback control model] 0 to rated current range, A								
M1-7	W-phase load current value	Ÿ-B	o to rated current range, A								
M1-8	Load power value	F - ñ	[Feedback control model] 0 to rated Power range, kW								
M1-9	Resistance value percentage	L-r	[Feedback control model] 0 to 100 % • Displays the present resistance as percentage compared to the set resistance of full load auto recognition.								
M1-10	Heatsink temp.	ŁñP	0 to 100 °C								
M1-11	Power supply frequency	Fr9	50, 60 Hz								

■ Parameter 1 group

Paran	neter	Display	Default	Setting range							
P1-1	SOFT START time	5-E	3	[Normal and Cycle control model] 0 to 100 sec							
P1-2	SOFT UP time U - E			SOFT UP time U - E		[Feedback control model]					
P1-3	SOFT DOWN time	d-E	3	0 (reach target output value quickly) to 100 (reach target output value slowly)							
P1-4	Output low-limit value	L-L	0	0 ≤ I-I ≤ H-I ≤ 100 %							
P1-5	Output high-limit value	H-L	100	0 S L-L S N-L S 100 %							
P1-6	Output slope ⁰¹⁾	SLP	100	0 to 100 % • In case of auto control (AUTO), set the output slop limit proportional to control input for limit load power.							

■ Parameter 2 group

Param	eter	Display	Default	Setting	range					
· uiuiii		Diopius	Delaute		4 - 20 mA					
P2-1	Control input ⁰¹⁾	Int	420	1-5: 1 - 5 VDC== 512: 5 - 12 VDC== (contact - voltage) ONF: ON / OFF (contact - non-voltage) COM: RS485 communication						
				*[Feedback control model]						
				Set Control method						
				PA		Normal				
				V-F*	Phase	Constant voltage feedback				
P2-2	Control method	E - ñ	PR	C-F*	control	Constant current feedback				
				W-F*		Constant power feedback				
				F-C	Cycle control	Fixed cycle				
				ONF	ON / OFF	control				
				_	put contro					
P2-3	Manual control (MAN) input ⁰¹⁾	ñAn	1 _ r	E_R: Ext	ernal adjus	ster o				
	·			E_I: Out	put contro	l / external adjuster				
P2-4	Input correction (1)	Inb	0.0	-99 to 99	06					
P2-5	Input slope correction	5Pn	0.0	-99 10 93	7 70					
P2-6	Front display	d! S	In	"[Feedback control model] IN: Resistance and input U-V': U-V line load voltage V-W': V-W line load voltage W-U': W-U line load voltage U-A': U-phase load current V-A': V-phase load current W-A': W-phase load current L-W': Load power						
P2-7	Over current alarm	ه ۲ ت	120	[Feedback control model]						
P2-8	value Over current alarm delay time	οCt	5	0 to 120 % [Feedback control model] 0 to 100 sec						
P2-9	Over voltage alarm value	000	120	[Feedback control model] 0 to 120 %						
P2-10	Over voltage alarm delay time	out	5	[Feedback control model] 0 to 100 sec						
P2-11	Load resistance value auto recognition	F-L	oFF	[Feedback control model] OFF, ON • It executes 100 % control output for 3 sec and the load resistance value recognized automatically as the initial set when the function is ON.						
P2-12	Heater break alarm value	НЬи	10	[Feedback control model] 10 to 100 %, OFF						
P2-13	Load unbalance alarm value	UL	0		ck control sed, 1 to 50					
P2-14	Output when load unbalance alarm occurs	ULo	on	ON: Nor	ck control mal operat tput stops	tion				
P2-15	Frequency error alarm disable / enable	Fr9	٥٥	OFF: Dis	able	X/				
P2-16	Comm. address	Adr	0 1	[RS485 of 01 to 99	communica	ation output model]				
P2-17	Comm. speed	6P5	96	24, 48, 9	6, 192, 384	ation output model] bps (× 100)				
P2-18	Comm. parity bit	PrE	non	[RS485 communication output model] NON, EVE, ODD						
P2-19	Comm. stop bit	SEP	2	[RS485 communication output model] 1, 2 bit						
P2-20	Comm. response time	r ï.E	20	[RS485 communication output model] 5 to 99 ms						
P2-21	Comm. write	E v. 7	E n.A	[RS485 communication output model] EN.A: Enable, DS.A: Disable						
P2-22	Lock	LoE	oFF	OFF LC1: Locks parameter 1 group LC2: Locks parameter 2 group						
1 2 22				LCZ. LUC	ль раганте	ter z group				

01) Set the below parameters available depends on the control input.

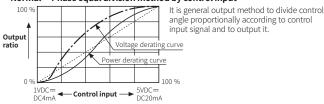
Туре	Control input			ay	Input correction	Input slope correction	Output slope	Monitoring value	
	Current	DC 4 - 20 mA		420	0	0	0		
	Voltage	Voltage 1 - 5 VDC==		1-5	0	0	0		
Auto control	Contact - voltage	5 - 12 VDC==	INT	512	×	×	0		
(AUTO)	Contact - non-voltage	ON / OFF		ONF	×	×	0	The last	
	RS485 comm		COM	×	×	×	control		
Manual	ual -	Output control adjuster (OUT ADJ)		I_R				input value 0 to 100 %	
control (MAN)	Output	External adjuster	MAN	E_R	×	×	×		
		Output control (OUT ADJ) / external adjuster		E_I					

Control Method

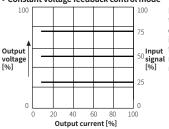
■ Phase control

Phase control method is to control output by dividing AC phase by control input signal.

• Normal = Phase equal division method by control input

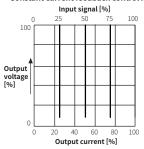


· Constant voltage feedback control mode



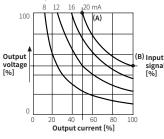
It outputs a constant voltage proportional to the control input so that the output voltage does not fluctuate against fluctuations in power voltage and load resistance fluctuations of loads (iron, chromium, signal nichrome, etc.) with a small electrical [%] resistance temperature coefficient.

· Constant current feedback control mode



It outputs a constant current proportional to the control input so that the output current does not fluctuate against fluctuations in power voltage and load resistance fluctuations of loads (platinum, molybdenum, tungsten, etc.) in which the temperature coefficient of electrical resistance varies significantly from 6 to 12 times the normal

• Constant power feedback control mode



It is proper control method for a heater which resistance value variation by silicon carbide (SiC) heating is big.

It outputs constant power which is proportion to control input even though load variation

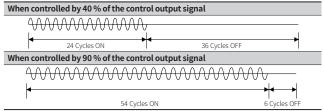
- × output current 50 %]
 (B): [output voltage 50 %
- × output current 100 %]
- Output characteristics is proper 50 % of the curve which connects the point (A) and the point (B). The current output capacity of this unit should be over two times of load capacity.

■ Cycle control, zero cross turn-on

Compared to the phase control method, the load control linearity is better. Since it is always ON or OFF at the zero point of AC, no noise is generated during ON / OFF, so it is a suitable control method for an environment where noise is not affected or an electric furnace with a large heat capacity.

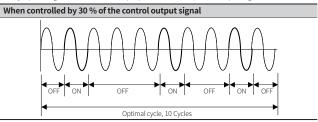
· Fixed cycle control mode

During fixed cycle (60 cycles) of load power, it repeats ON / OFF cycle as constant ratio according to control input signal and controls the power supplies on the load.



Variable cycle control mode

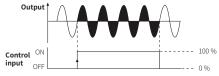
By optimizing the number of cycles of the load power, it controls the power applied to the load by operating ON / OFF at a ratio proportional to the control input signal.



■ ON / OFF control, zero cross turn-on

This is control method that output is 100 % at control input ON, and 0 % at control input OFF. It is the same function as SSR (Solid State Relay). It always turns ON or OFF at zero point of AC.

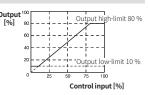
• When using ON / OFF control method, output control, SOFT START, SOFT UP / DOWN, input correction, and input slope correction functions are not setable.



Function

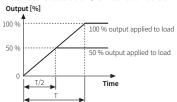
■ Output high / low-limit value

This function is to limit output range to protect load.t



SOFT START

- This function protects the load in cases that the set temperature is high, such as controlling the load (platinum. molybdenum, tungsten, infrared lamp, etc.) in which inrush current flows when power is supplied, or showing large width of temperature rise during initial
- SOFT START set time (T) is the required time that output reaches to 100 %.
 It is not available at ON / OFF control method.

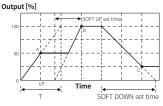


- T: SOFT START set time. Time to get the output which is
- applied into the load is 100 % • T/2: Time to get the output which is applied into the load is 50 %.

■ SOFT UP / DOWN

Unlike SOFT START which operates only once at supplying power, this function protects load from the inrush current in the RUN mode. When reached to the target output value, operation stops.

• It is not available at ON / OFF control method.

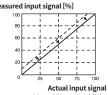


- T: SOFT START set time
- · A: SOFT START function finished B: SOFT UP function finished C: SOFT DOWN function finished

■ Input correction

It compensates the offset between actual input value and measured input value.

E.g.) When input monitoring value is 5 % at 4 mA in DC4 - 20 mA control input, setting INB = -5 calibrates the input monitoring value to 0 %.



Input slope correction

It compensates the gain of the measured 100 % input for actual 100 % input value.
Calibrated monitoring value = Monitoring value +

monitoring value 100 - input slope correction value

X Input slope correction value

x Input slope correction value

E.g.) When the input monitoring value is 99 % at 20 mA in DC 4 - 20 mA control input, setting input slope correction value = 1 calibrates the input monitoring value to 100 %.

Actual input signal [%] Actual input signal (%) Input corrected signal (%)

red input signal [%] Actual input signal [%]

-: Actual input signal (%) -: Input corrected signal (%)

Segment Table

The segments displayed on the product indicate the following meanings. It may differ depending on the product.

7 se	7 segment			11	segi	men	t	12 segment 16 segmen						it	
0	0	1	T	0	0	1	П	0	0	1	П	0	0	I	Π
-1	1	J	J	-1	1	J	J	-1	1	J	J	-1	1	ŭ	J
2	2	F	K	2	2	К	К	2	2	К	K	2	2	K	K
3	3	L	L	3	3	L	L	3	3	L	L	3	3	L	L
4	4	ñ	М	Ч	4	М	М	Ч	4	М	М	Ч	4	М	М
5	5	n	N	5	5	N	N	5	5	N	N	5	5	N	N
5	6	0	0	6	6	0	0	Б	6	0	0	5	6	0	0
7	7	Р	Р	7	7	Ρ	Р	7	7	Ρ	Р	7	7	Р	Р
8	8	9	Q	8	8	0	Q	8	8	0	Q	8	8	Q	Q
9	9	٦	R	9	9	R	R	9	9	R	R	9	9	ĸ	R
R	Α	5	S	Я	Α	5	S	Я	Α	5	S	Я	Α	5	S
Ь	В	Ł	Т	Ь	В	Ł	Т	Ь	В	Ł	Т	3	В	Ţ	Т
Е	С	U	U	Е	С	Ш	U	Е	С	Ш	U	С	С	Ш	U
d	D	u	V	Ь	D	V	٧	d	D	V	V	D	D	r	٧
Ε	Е	ū	W	Ε	Е	И	W	Ε	Е	И	W	Ε	Е	И	W
F	F	4	Х	F	F	×	Х	F	F	×	Х	F	F	×	Х
G	G	У	Υ	G	G	У	Υ	5	G	У	Υ	5	G	Y	Υ
Н	Н	Ξ	Z	Н	Н	Z	Z	Н	Н	Z	Z	Н	Н	2	Z