# **SPR3 Series INSTRUCTION MANUAL**

TCD210147AD

<u>Autonics</u>

Thank you for choosing our Autonics product.

Read and understand the instruction manual and manual thoroughly before using the product.

For your safety, read and follow the below safety considerations before using. For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

Keep this instruction manual in a place where you can find easily.

The specifications, dimensions, etc. are subject to change without notice for product improvement. Some models may be discontinued without notice. Follow Autonics website for the latest information.

# Safety Considerations

• Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.

•  $\Lambda$  symbol indicates caution due to special circumstances in which hazards may occur.

**Warning** Failure to follow instructions may result in serious injury or death.

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime / disaster prevention devices, etc.) Failure to follow this instruction may result in personal injury, economic loss or fire. 02. Do not use the unit in the place where flammable / explosive / corrosive gas,
- high humidity, direct sunlight, radiant heat, vibration, impact or salinity may **be present.** Failure to follow this instruction may result in explosion or fire.

03. Install on the device panel, and ground to the bolt for grounding separately.

- ilure to follow this instruction may result in fire or electric shoc 04. Do not connect, repair, or inspect the unit while connected to a power source.
- ure to follow this instructio may result in fire or electric shock. 05. Check 'Connections' before wiring.
- sult in fire 06. Do not disassemble or modify the unit.
- Failure to follow this instruction may result in fire or electric shock.

▲ Caution Failure to follow instructions may result in injury or product damage.

#### 01. Use the unit within the rated specifications.

- illure to follow this instruction may result in fire or product damage 02. Use a dry cloth to clean the unit, and do not use water or organic solvent.
- result in fire or electric sho 03. Keep the product away from metal chip, dust, and wire residue which flow into the unit.
- Failure to follow this instruction may result in fire or product damage. 04. Since leakage current still flows right after turning off the power or in the output OFF status, do not touch the load terminal. ure to follow this instruction may result in electric shock

# **Cautions during Use**

• Follow instructions in 'Cautions during Use'.

- Otherwise, it may cause unexpected accidents
- Use the product, after 3 sec of supplying power.
  Before use, set the mode and function according to the specification. Especially, be cautious that the product does not operate when output control adjuster (OUT ADJ) is set to 0 %. Since changing the mode / parameter during operation may result in malfunction, set the mode and function after disconnecting load output.
- Re-supply the power to the unit after the unit is discharged completely. Failure to follow this instruction may result in malfunction.
- To ensure the reliability of the product, install the product on the panel or metal surface vertically to the ground. • Install the unit in the well ventilated place.
- While supplying power to the load or right after turning off the power of the load, do
  not touch the body and heat sink. Failure to follow this instruction may result in a burn
  due to the high temperature.
- · Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power. • Do not wire to terminals which are not used.
- Use twisted pair wire for communication line.
  Since inter element can be damaged when using with coil load, inductive load, etc.,
- the inrush current must be under the rated load current.
- Do not use near the equipment which generates strong magnetic force or high frequency noise.
- This unit may be used in the following environments. - Indoors (in the environment condition rated in 'Specifications')
- Altitude max. 2,000 m
- Pollution degree 2
- Installation category III

#### Ordering Information

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website.

|   | -                 | -      |        |          |    |                            |  |
|---|-------------------|--------|--------|----------|----|----------------------------|--|
| SPR   | 3                 | -      | 0      | 0        | 8  | 4                          | 0  |
| <b>O</b> Rate<br>1: 110 V/<br>2: 220 V/<br>3: 380 V/<br>4: 440 V/ | AC~<br>AC~<br>AC~ | /oltag | je     |          |    | N: Nor<br>F: Norr          | <b>dback control</b><br>mal control<br>mal, feedback control (constant<br>ent / constant voltage / constant<br>er) |
| 2 Rate<br>Numbe   |                   |        |        | unit: A) |    | G Fus<br>N: Non<br>F: Supp | -  |
| Option<br>N: Alarm<br>T: Alarm                                    | n output          | t      | 85 com | m. outp  | ut |                            |  |

# **Product Components**

 Product • 11-pin connector  $\times$  1  Instruction manual • Insulating barrier  $\times$  4

#### Manual

For proper use of the product, refer to the manuals and be sure to follow the safety considerations in the manuals. Download the manuals from the Autonics website.

# Software

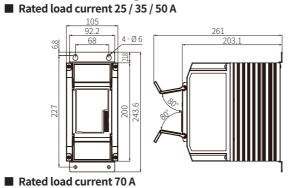
Download the installation file and the manuals from the Autonics website

# DAQMaster

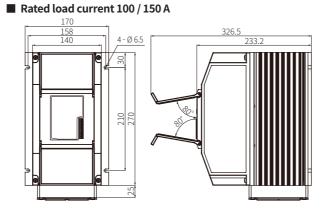
It is the comprehensive device management program for Autonics' products, providing parameter setting, monitoring and data management.

# Dimensions

• Unit: mm, For the detailed drawings, follow the Autonics website



1 - Ø 6 68

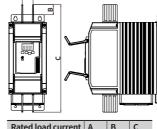


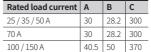
#### Insulating Barrier

It is recommended to use the included interphase barriers for insulation between phases and reduce influence from conductive material

• Unit: mm, For the detailed drawings, • With the insulating barrier follow the Autonics website.







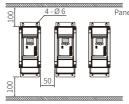
# **Cautions during Installation**

# High Temperature Caution

While supplying power to the load or right after turning off the power of the load, A on ot touch the body and heatsink. Failure to follow this instruction may result in a burn due to the high temperature.

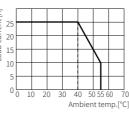
#### Mount space

- Unit: mm
- When installing multiple power controllers, keep space between power controllers for heat radiation Horizontal:  $\geq$  50 mm, vertical:  $\geq$  100 mm

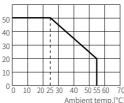


#### **Derating Curve**

# Rated load current 25 A

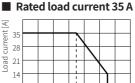


# Rated load current 50 A



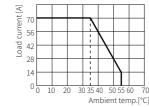
# Rated load current 100 A

| ≥    |                 |     |     |    |        |              |              |        | 1  |
|------|-----------------|-----|-----|----|--------|--------------|--------------|--------|----|
| ent  | L00             | -   |     |    |        |              |              |        |    |
| curr | 100<br>80<br>60 | -   | -   |    | ÷      | $\mathbf{h}$ |              |        |    |
| bad  | 60              | -   | -   |    | +      |              | -            |        |    |
| 2    | 40              | -   | -   |    | i      |              | $\mathbf{h}$ |        |    |
|      | 20              | -   | -   |    | +      |              | +            |        |    |
|      | 0               | 0 1 | 0 2 | 03 | 0 35 4 |              |              |        | 70 |
|      |                 |     |     |    | Am     | nbien        | it ter       | np.[°( | CJ |

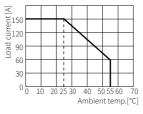


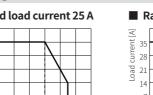
Ambient temp.[°C]

#### Rated load current 70 A



# Rated load current 150 A





# Specifications

| Rated toad voltage 60 Hz 60 Hz 60 Hz 60 Hz   | 3-4  |  |  |  |  |  |
|--|--|--|--|--|--|--|
| Rated load voltage         110 VAC~ 50 /<br>60 Hz         220 VAC~ 50 /<br>60 Hz         380 VAC~ 50 /<br>60 Hz         440 V<br>60 Hz   |  |  |  |  |  |  |
| Rated toad voltage 60 Hz 60 Hz 60 Hz 60 Hz   |  |  |  |  |  |  |
|  | /AC~ 50 /  |  |  |  |  |  |
| <b>Rated load current</b> 25 / 35 / 50 / 70 / 100 / 150 A  |  |  |  |  |  |  |
| Display method 3-digit 7segment LED  |  |  |  |  |  |  |
| Indicators Operation / manual control indicator (green)<br>Alarm / output / unit (V, A) indicator (red)  |  |  |  |  |  |  |
| Auto control input Current: DC 4 - 20 mA, voltage: 1 - 5 VDC=, contact (non-voltage contact (voltage): 5 - 12 VDC=, communication: RS485   |  |  |  |  |  |  |
| $\begin{tabular}{lllllllllllllllllllllllllllllllllll$  | )  |  |  |  |  |  |
| Digital input (DI) RUN / STOP selectable, AUTO / MAN selectable, RESET   |  |  |  |  |  |  |
| Alarm output 250 VAC~ 3 A, 30 VDC= 3 A, 1c resistance load   |  |  |  |  |  |  |
| RS485 comm. output Modbus RTU method   |  |  |  |  |  |  |
| Cooling method Rated load current 25 / 35 / 50 A: natural cooling Rated load current 70 / 100 / 150 A: forced air cooling (with c  | cooling fan)   |  |  |  |  |  |
| Unit weight<br>(packaged)Rated load current $25 / 35 / 50 A$ : $\approx 4.1 \text{ kg} (\approx 4.9 \text{ kg})$<br>Rated load current $70 A$ : $\approx 4.2 \text{ kg} (\approx 5 \text{ kg})$<br>Rated load current $100 / 150 A$ : $\approx 8.7 \text{ kg} (\approx 9.7 \text{ kg})$  |  |  |  |  |  |  |
| Approval CE  |  |  |  |  |  |  |
| Control worked Dhave control Control control   | atual  |  |  |  |  |  |
| Control method Phase control Cycle control ON/OFF con  | וניסו  |  |  |  |  |  |
| Control mode constant current feedback/<br>constant voltage feedback/<br>constant powerfeedback  |  |  |  |  |  |  |
| Applied load Resistance load, inductive load Resistance load Resistance load   |  |  |  |  |  |  |
| Output range         0 to 98 %         0 to 100 %         0 / 100 %  |  |  |  |  |  |  |
| Phase control<br>output accuracy         • Normal control: within ± 10 % F.S. of rated load voltage           • Constant current feedback control: within ± 3 % F.S. of rated load<br>• Constant voltage feedback control: within ± 3 % F.S. of rated load<br>• Constant power feedback control: within ± 3 % F.S. of rated load | d voltage  |  |  |  |  |  |
| <b>Power supply</b> 100 - 240 VAC~ ±10 % 50 / 60 Hz  |  |  |  |  |  |  |
| Min. load current 1A   |  |  |  |  |  |  |
| Power<br>consumptionRated load current $25 / 35 / 50 A: \le 14$ VA<br>Rated load current $70 A: \le 22$ VA<br>Rated load current $100 / 150 A: \le 32$ VA  |  |  |  |  |  |  |
| $\frac{\text{Insulation}}{\text{resistance}} \geq 200 \text{ M}\Omega \text{ (500 VDC== megger)}$  |  |  |  |  |  |  |
| <b>Dielectric strength</b> Between input and power terminal: 2,000 VAC $\sim$ 50 / 60 Hz f   | for 1 min  |  |  |  |  |  |
| Output leakage<br>currents         ≤ 10 mArms  |  |  |  |  |  |  |
| <b>Noise immunity</b> $\pm 2$ kV square wave noise (pulse width: 1 µs) by the noise sin  | mulator  |  |  |  |  |  |
| <b>Memory retention</b> $\approx$ 10 years (when using non-volatile semiconductor memor  | 2 21   |  |  |  |  |  |
|  | 0.75 mm double amplitude at frequency of 5 to 55 Hz (for 1 min) in<br>each X, Y, Z direction for 2 hours |  |  |  |  |  |
|  | 0.5 mm double amplitude at frequency of 5 to 55 Hz (for 1 min) in each                                   |  |  |  |  |  |
| each X, Y, Z direction for 2 hours   | nin) in each   |  |  |  |  |  |
| Vibration         each X, Y, Z direction for 2 hours           Vibration         0.5 mm double amplitude at frequency of 5 to 55 Hz (for 1 n   |  |  |  |  |  |  |

#### **Communication Interface**

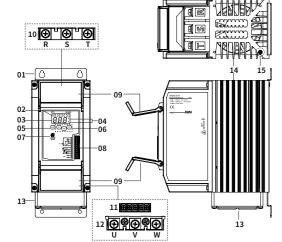
#### RS485

| Comm. protocol           | Modbus RTU                                  |
|--------------------------|---|
| Application standard     | Compliance with EIA RS485                   |
| Max. connection          | 31-unit (address: 01 to 99)                 |
| Comm. synchronous method | Asynchronous                                |
| Comm. method             | 2-wire half duplex                          |
| Comm. distance           | ≤ 800 m                                     |
| Comm. speed              | 2,400 / 4,800 / 9,600 / 19,200 / 38,400 bps |
| Comm. response time      | 5 to 99 ms (default: 20 ms)                 |
| Start bit                | 1-bit (fixed)                               |
| Data bit                 | 8-bit (fixed)                               |
| Parity bit               | None, Even, Odd                             |
| Stop bit                 | 1-bit, 2-bit                                |

# Load Output Formula

| Туре           | Input   |  | Formula   |  |  |
|----------------|---------|--|---|--|--|
|                | Current | DC 4 - 20 mA                                       | Load output [%]   |  |  |
| Auto<br>(AUTO) | Voltage | 1-5VDC==   | = Control input [%] × output slope [%]                                  |  |  |
| (/1010)        | RS485 c | ommunication                                       | Load output [%] = RS485 [%]   |  |  |
|                |         | Output control<br>adjuster (OUT ADJ)               | Load output [%] = output control adjuster [%]                           |  |  |
| Manual         | Output  | External adjuster                                  | Load output [%] = external adjuster [%]                                 |  |  |
| (MAN) control  |         | Output control<br>(OUT ADJ) /<br>external adjuster | Load output [%]<br>= output control adjuster [%] × External adjuster [% |  |  |

# Unit Descriptions



01. Bracket [except rated load current 100 / 150 A model]

| 02. Ind | icator                           |   |
|---------|----------------------------------|---|
| Indicat | or                               | Function  |
| RUN     | Operation indicator (green)      | Turns on in the RUN mode.                                       |
| MAN     | Manual control indicator (green) | Turns on when adjusting load output in the manual control mode. |
| ALM     | Alarm indicator (red)            | Flashes in alarming status.                                     |
| OUT     | Output indicator (red)           | Turns on when load control outputs.                             |

## 03. Display part

RUN mode: Displays depending the front display setting Setting mode: Displays parameter and setting value

| D4. Unit indicator (V<br>Dependent on the disp                                   |     | ng. | 07. Output control adjuster (OUT A<br>Adjusts output from 0 to 100% in manu  |
|--|-----|-----|--|
| Display setting  | V   | A   | control.   |
| Resistance and input   | OFF | OFF | 08. Control input /  |
| Voltage  | ON  | OFF | comm. output terminal  |
| Current  | OFF | ON  | (11-pin connector terminal)<br>09. Terminal protection cover   |
| Power  | ON  | ON  | 10. R, S, T load input terminal  |
| 05. [MODE] key<br>Enters parameter grou<br>mode, moves paramet<br>setting value. |     |     | 11. Alarm output / power input tern<br>12. U, V, W load output terminal<br>13. Cooling fan<br>[Rated load current 70 / 100 / 150 A mod |

06. [◀], [▼], [▲] key

Enters SV setting mode and move digits.

left / right mounting holes. 15. Bolt for grounding (M4)

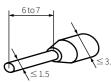
14. Heatsink

Rated load current 100 / 150 A models have

# **Cautions during Wiring**

#### Control input / comm. output terminal (11-pin connector)

• Unit: mm, Use penhole terminals of size specified below.



# Alarm output / power input & U, V, W load output terminal

· Unit: mm, Use crimp terminals of size specified below.

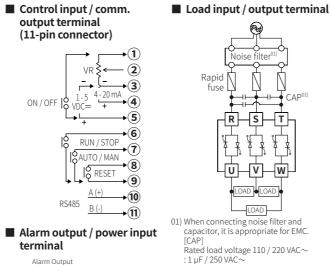
| $\mathcal{N}$ | Rated load current  | Spec. | Alarm output / power input | Load input /<br>output |
|---------------|---------------------|-------|----------------------------|------------------------|
| 6             | 25/35/50/           | а     | ≥ 3.0                      | ≥ 6.0                  |
|               | 70 A<br>100 / 150 A | b     | $\leq 6.0$                 | $\leq 16.0$            |
|               |                     | а     | ≥ 3.0                      | ≥ 8.0                  |
| 2             |                     | b     | $\leq 6.0$                 | ≤ 26.0                 |

 Cable / screw / tightening torque spec. is different depending on the load current. Be sure to the below before connection.

| Rated load current  | Spec.                | Alarm output /<br>power input | Load input / output |
|---------------------|----------------------|-------------------------------|---------------------|
|                     | Cable                | AWG 18 to 14                  | AWG 13 to 4         |
| 25 / 35 / 50 / 70 A | Screw                | M3                            | M6                  |
| 237 337 367 1011    | Tightening torque    | 0.5 N m                       | 5.5 to 6.0 N m      |
|                     | Cable                | AWG 18 to 14                  | AWG 4 to 2 / 0      |
| 100 / 150 A         | Screw                | M3                            | M8                  |
|                     | Tightening<br>torque | 0.5 N m                       | 6.5 to 7.0 N m      |

#### Connections

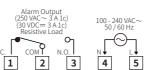
• Terminal configuration by model may differ depending on the supported spec.



-| T |

Rated load voltage 380 / 440 VAC  $\sim$ 

: 0.47 uF / 500 VAC~



# Alarm

. played based

|          | -                     | <b>D</b> <sup>1</sup> | Operation   |                          |  | Madal                        |  |
|----------|-----------------------|-----------------------|---|--------------------------|--|------------------------------|--|
| Priority | Туре                  | Display               | Alarm   | Output                   | Alarm release  | Model                        |  |
| 1        | SCR error             | 5[r                   |   |                          |  | Feedback control             |  |
| 2        | Over<br>current       | o - C                 |   | Output                   |  | Feedback control             |  |
| 4        | Heatsink<br>over heat | ŁĒñ                   | Error<br>display<br>flashes.<br>Alarm<br>indicator<br>(ALM)<br>flashes.<br>Stopp<br>Outp<br>flashes.<br>Alarm | stops.<br>(SCR OFF)      | <ul> <li>Re-supply<br/>power.</li> <li>RESET input</li> <li>Switch to stop<br/>(STOP) mode.</li> </ul> | Normal /<br>Feedback control |  |
| 5        | Over<br>voltage       | 0 <sup>-</sup> U      |   |                          |  |                              |  |
| 7        | Load<br>unbalance     | UL                    |   | M) Output<br>hes. stops. |  | Feedback control             |  |
| 3        | Fuse<br>break         | FUS                   | output<br>turns ON  | Output                   | Automatically  | Normal /                     |  |
| 8        | Frequency<br>error    | Fr9                   |   | stops.<br>(SCR OFF)      | cleared when<br>returning within   | Feedback control             |  |
| 6        | Heater<br>break       | Н-Ь                   |   | Normal operation         | the setting range  | Feedback control             |  |

SCR error alarm

Even though output is 0 %, if the current of 10 % or more of the rated load current flows for over 3 sec continuously, SCR error alarm occurs.

Over current alarm

- This function protects the load from over current. If the current flows over the P2-7 over current alarm value and P2-8 over current alarm delay time, over current alarm occurs. Heatsink over heat alarm
- When the temperature of a heatsink is over 85 °C, heatsink over heat alarm occurs. Over voltage alarm
- This function protects the load from over voltage. If the current flows over the P2-9 over voltage alarm value and P2-10 over voltage alarm delay time, over voltage alarm occurs. • Load unbalance alarm
- If the current of U, V, W is [load unbalance value  $\geq$  P2-13 load unbalance alarm value], the alarm occurs.
- When the alarm occurs, the load output operates as according to the set of P2-14 output when load unbalance alarm occurs.  $\rightarrow$  ON: normal operation, OFF: output stops (SCR OFF)

- Load unbalance value (A) =  $I_{max} I_{min}$ ( $I_{max}$ : maximum phase load current value,  $I_{min}$ : minimum phase load current value) E.g.) R phase: 7 A, S phase: 2 A, T phase: 3 A, P2-13 load unbalance alarm value: 2 A Load unbalance value = 7 - 2 = 5 A

Load unbalance value > P2-13 load unbalance alarm value and the alarm occurs. Fuse break alarm

When breaking fuse, not suppling load power, breaking load (single load), fuse brake alarm occurs. In the case of normal control model, real-time fuse break alarm is not available during output, and fuse break alarm operates at 0 % output such as RESET. Heater break alarm

Comparing the full load resistance value and the current load resistance value, if the current load resistivity is maintained under the P2-12 heater break alarm value for over 3 sec continuously, heater break alarm occurs. This alarm operates when control output is over 10 % and load current is over 10 % of the rated current. Output does not stop and operates normally

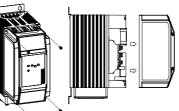
Current load resistance (%) =  $\frac{\text{Full load resistance value} \times 100}{2}$ 

#### Frequency error alarm

When the load power frequency is out of the specification, frequency error alarm occurs.

#### **Replacement of Fuse**

#### Case removal



#### Replacement of fuse

• Fuse none model is not equipped with a rapid fuse inside. Install the suitable fuse for rated load current of the model separately.

• The performance of the product is guaranteed only when using the fuse provided by us. For replacing the fuse, use the recommended fuse.

|              | ,          |                    |           |              |
|--------------|------------|--------------------|-----------|--------------|
|              |            | Rated load current | Rec. fuse | Manufacturer |
| <b>ALELE</b> | ALLEL A    | 25 A               | 50FE      |              |
| S S S        |            | 35 A               | 63ET      | BUSSMANN     |
| Fuse         |            | 50 A               | 80ET      | DUSSMAININ   |
|              |            | 70 A               | 100FE     |              |
| ess          |            | 100 A              | 660GH-160 | HINODE       |
| NUL          | Fuse       | 150 A              | 660GH-200 | HINODE       |
|              | fixed bolt |                    |           |              |

#### Bolt specification

| Rated load current  | Case fixed bolt | Fuse fixed bolt       |  |
|---------------------|-----------------|-----------------------|--|
| 25 / 35 / 50 / 70 A | М3              | M6                    |  |
| 100 A               | M4              | Top: M8<br>Bottom: M6 |  |
| 150 A               | M4              | M8                    |  |

#### Mode Setting

|     | [MODE]                                   | →             | Monitoring group         | [MODE] 3 sec | $\rightarrow$ |     |
|-----|--|---------------|--------------------------|--------------|---------------|-----|
|     | [MODE] 2 sec                             | →             | Parameter 1 group        | [MODE] 3 sec | $\rightarrow$ |     |
|     | [MODE] 4 sec                             | →             | Parameter 2 group        | [MODE] 3 sec | →             |     |
| RUN | [ <b>◀</b> + <b>▲</b> + <b>▼</b> ] 5 sec | $\rightarrow$ | Parameter reset          | [MODE]       | $\rightarrow$ | RUN |
|     | 6 - 9 terminal<br>external contact       | →             | RUN / STOP               | Auto         | $\rightarrow$ |     |
|     | 7 - 9 terminal<br>external contact       | →             | Auto / Manual<br>control | Auto         | $\rightarrow$ |     |
|     | [▲+▼] 2 sec or<br>8 - 9 terminal         | →             | Reset <sup>01)</sup>     | Auto         | →             |     |
|     |  |               |                          |              |               |     |

01) In the event of system anomalies and alarms, RESET input restarts the power controller. (parameters are not

# Parameter Setting

 Some parameters are activated / deactivated depending on the model or setting of other parameters. Refer to the description of each parameter.

- If any key is not entered for 30 sec in each parameter, it returns to RUN mode.
- [MODE] key: Saves current setting value and moves to the next parameter.
   [4] key: Changes setting digits.
- [▲], [▼] key: Changes setting values.

#### Monitoring group

| Param                            | eter                             | Display | / Display range   |  |  |  |  |  |
|----------------------------------|----------------------------------|---------|---|--|--|--|--|--|
| M1-1                             | Monitoring value                 | l n     | 0 to 100 %  |  |  |  |  |  |
| M1-2                             | U-V line load voltage value      | U-u     |   |  |  |  |  |  |
| M1-3 V-W line load voltage value |                                  | u - U   | [Feedback control model]<br>0 to rated voltage range, V   |  |  |  |  |  |
| M1-4                             | 11-4 W-U line load voltage value |         | o to rated voltage range, v   |  |  |  |  |  |
| M1-5                             | U-phase load current value       | U - A   | [Feedback control model]<br>0 to rated current range, A   |  |  |  |  |  |
| M1-6                             | V-phase load current value       | u - R   |   |  |  |  |  |  |
| M1-7                             | W-phase load current value       | ⊻-R     |   |  |  |  |  |  |
| M1-8                             | Load power value                 | L - 9   | [Feedback control model]<br>0 to rated Power range, kW  |  |  |  |  |  |
| M1-9                             | Resistance value percentage      | L-r     | [Feedback control model]<br>0 to 100 %<br>• Displays the present resistance as percentage<br>compared to the set resistance of full load auto<br>recognition. |  |  |  |  |  |
| M1-10                            | Heatsink temp.                   | ΕñΡ     | 0 to 100 °C   |  |  |  |  |  |
| M1-11                            | Power supply frequency           | Fr 9    | 50, 60 Hz   |  |  |  |  |  |

| -lai II |             |         |       |                                 |                                 |      |
|---------|-------------|---------|-------|---------------------------------|---------------------------------|------|
|         | several ala |         | 1     | iding on the i<br>me, the highe | model.<br>est priority error is | disp |
|         | Turne       |         |       |                                 |                                 |      |
| riority | Туре        | Display | Alarm | Output                          | Alarm release                   | Mo   |
|         | SCR error   | SEr     |       |                                 |                                 | Fee  |
|         | Over        | o-E     |       |                                 |                                 | Fee  |

# Parameter 1 group

| Paran | neter                       | Display | Default | Setting range   |  |  |
|-------|-----------------------------|---------|---------|---|--|--|
| P1-1  | SOFT START time             | 5 - E   | Э       | [Normal and Cycle control model]<br>0 to 100 sec  |  |  |
| P1-2  | SOFT UP time                | U - E   | З       | [Feedback control model]  |  |  |
| P1-3  | SOFT DOWN time              | d - E   | З       | 0 (reach target output value quickly) to<br>100 (reach target output value slowly)  |  |  |
| P1-4  | Output low-limit<br>value   | L-L     | 0       | 0 ≤ I-I ≤ H-I ≤ 100 %   |  |  |
| P1-5  | Output high-limit<br>value  | H-L     | 100     | $-0 \le L-L \le H-L \le 100\%$  |  |  |
| P1-6  | Output slope <sup>01)</sup> | SLP     | 100     | 0 to 100 %<br>• In case of auto control (AUTO), set the output<br>slop limit proportional to control input for limit<br>load power. |  |  |

#### Parameter 2 group

| Param | leter   | Display | Default | Setting range  |  |  |  |
|-------|---|---------|---------|--|--|--|--|
|       |   |         |         | 420: DC 4 - 20 mA  |  |  |  |
| P2-1  | Control input <sup>01)</sup>                  | Int     | 420     | 1-5: 1 - 5 VDC==<br>512: 5 - 12 VDC==<br>ONF: ON / OFF (contact - voltage)<br>COM: R5485 communication   |  |  |  |
| P2-2  | Control method                                | [-ō     | PR      | *[Feedback control model]           Set         Control method           PA         Normal           V-F*         Phase           Constant voltage feedback           C-F*         Constant current feedback           F-C         Cycle<br>control         Fixed cycle           ONF         ON / OFF control |  |  |  |
| P2-3  | Manual control (MAN)<br>input <sup>01)</sup>  | ñßn     | 1_r     | I_R: Output control adjuster<br>E_R: External adjuster<br>E_I: Output control / external adjuster  |  |  |  |
| P2-4  | Input correction <sup>01)</sup>               | Inb     | 0.0     |  |  |  |  |
| P2-5  | Input slope correction                        | 5Pn     | 0.0     | -99 to 99 %  |  |  |  |
| P2-6  | Front display                                 | di 5    | In      | *[Feedback control model]<br>IN: Resistance and input<br>U-V:: U-V line load voltage<br>W-U:: W-U line load voltage<br>W-U:: W-U line load voltage<br>U-A:: U-phase load current<br>V-A:: V-phase load current<br>W-A:: W-phase load current<br>L-W:: Load power   |  |  |  |
| P2-7  | Over current alarm<br>value                   | ٥٢٥     | 150     | [Feedback control model]<br>0 to 120 %   |  |  |  |
| P2-8  | Over current alarm<br>delay time              | o[t     | 5       | [Feedback control model]<br>0 to 100 sec   |  |  |  |
| P2-9  | Over voltage alarm<br>value                   | ٥υυ     | 150     | [Feedback control model]<br>0 to 120 %   |  |  |  |
| P2-10 | Over voltage alarm<br>delay time              | out     | 5       | [Feedback control model]<br>0 to 100 sec   |  |  |  |
| P2-11 | Load resistance value auto recognition        | F-L     | oFF     | [Feedback control model]<br>OFF, ON<br>• It executes 100 % control output for 3 sec and the<br>load resistance value recognized automatically<br>as the initial set when the function is ON.   |  |  |  |
| P2-12 | Heater break alarm<br>value                   | НЬо     | 10      | [Feedback control model]<br>10 to 100 %, OFF   |  |  |  |
| P2-13 | Load unbalance<br>alarm value                 | UL      | 0       | [Feedback control model]<br>0: Not used, 1 to 50 A   |  |  |  |
| P2-14 | Output when load<br>unbalance alarm<br>occurs | ULo     | on      | [Feedback control model]<br>ON: Normal operation<br>OFF: Output stops (SCR OFF)  |  |  |  |
| P2-15 | Frequency error alarm<br>disable / enable     | Fr9     | ٥٩      | OFF: Disable<br>ON: Enable   |  |  |  |
| P2-16 | Comm. address                                 | Rdr     | 01      | [RS485 communication output model]<br>01 to 99   |  |  |  |
| P2-17 | Comm. speed                                   | 6Р5     | 96      | [RS485 communication output model]<br>24, 48, 96, 192, 384 bps (× 100)   |  |  |  |
| P2-18 | Comm. parity bit                              | Prt     | non     | [RS485 communication output model]<br>NON, EVE, ODD  |  |  |  |
| P2-19 | Comm. stop bit                                | 5EP     | 5       | [RS485 communication output model]<br>1, 2 bit   |  |  |  |
| P2-20 | Comm. response time                           | r Ľ.E   | 20      | [RS485 communication output model]<br>5 to 99 ms   |  |  |  |
| P2-21 | Comm. write                                   | [ ñ.º   | E n.R   | [RS485 communication output model]<br>EN.A: Enable, DS.A: Disable  |  |  |  |
| P2-22 | Lock  | LoC     | oFF     | OFF<br>LC1: Locks parameter 1 group<br>LC2: Locks parameter 2 group  |  |  |  |
| P2-23 | Parameter reset                               | 1.01    | 0.0     | NO YES   |  |  |  |

P2-23 Parameter reset Inl no NO, YES (1) Set the below parameters available depends on the co

| Туре             | Control input            |  |     |     | Input<br>correction | Input slope<br>correction | Output<br>slope | Monitoring value          |
|------------------|--------------------------|--|-----|-----|---------------------|---------------------------|-----------------|---------------------------|
|                  | Current                  | DC 4 - 20 mA                                       |     | 420 | 0                   | 0                         | 0               | The last                  |
|                  | Voltage                  | 1 - 5 VDC==  | ]   | 1-5 | 0                   | 0                         | 0               |                           |
| Auto<br>control  | Contact -<br>voltage     | 5 - 12 VDC===                                      | INT | 512 | ×                   | ×                         | 0               |                           |
| (AUTO)           | Contact -<br>non-voltage | ON / OFF   |     | ONF | ×                   | ×                         | 0               |                           |
|                  | RS485 communication      |  |     | COM | ×                   | ×                         | ×               | control                   |
| Manual           |                          | Output control<br>adjuster<br>(OUT ADJ)            |     | I_R | ×                   | ×                         | ×               | input value<br>0 to 100 % |
| control<br>(MAN) | Output<br>control        | External adjuster                                  | MAN | E_R |                     |                           |                 |                           |
|                  |                          | Output control<br>(OUT ADJ) /<br>external adjuster |     | E_I |                     |                           |                 |                           |

